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Effects of lighting illuminance levels on stair negotiation performance in individuals with visual impairment

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### 1 Title page

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#### 23 Abstract

*Background:* Stair-related falls of older people cause a substantial financial and social burden. Deterioration of the visual system amongst other factors put older people at a high risk of falling. Improved lighting is often recommended. The aim of this study was to investigate the effect of lighting illuminance on stair negotiation performance in older individuals with visual impairment.

30 *Methods:* Eleven participants aged 60 or over with a vision of 6/18 or worse 31 ascended and descended a staircase under: 50lx, 100lx, 200lx, 300lx and 32 distributed 200lx lighting. A motion capture system was used to measure 33 movements of the lower limb. Clearance, clearance variability, temporal and 34 spatial parameters and joint/segment kinematics were computed.

*Findings:* There was no effect on clearance or clearance variability. Participants had lower speed, cadence, increased cycle time and stance time in the 50lx compared to 300lx and distributed 200lx lighting in descent. The minimum hip angle in ascent was increased in the 200lx lighting. Clearance was found to be moderately correlated with balance scores.

*Interpretation* Individuals with visual impairment adopt precautionary gait in
 dim lighting conditions. This does not always result in improvements in the
 parameters associated with risk of falling (e.g. clearance).

43 Key words: lighting, vision, temporal-spatial parameters, clearance,

44 clearance variability, kinematics, stair ascent, stair descent

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#### 50 Abstract

*Background:* Stair-related falls of older people cause a substantial financial and social burden. Deterioration of the visual system amongst other factors put older people at a high risk of falling. Improved lighting is often recommended. The aim of this study was to investigate the effect of lighting illuminance on stair negotiation performance in a group of older individuals with visual impairment.

*Methods:* Eleven participants aged 60 or over with a vision of 6/18 or worse ascended and descended a staircase under five lighting conditions: 50lx, 100lx, 200lx, in 300lx and distributed 200lx lighting. A motion capture system was used to measure movements of the lower limb. Clearance, clearance variability, temporal and spatial parameters and joint/segment kinematics were computed.

*Findings:* There was no effect on clearance or clearance variability. Participants had lower speed, cadence, increased cycle time and stance time in dimmer lighting conditions in descent. The minimum hip angle in ascent was increased in optimal lighting conditions (200lx) compared to other lighting conditions. Clearance in this participant group was found to be moderately correlated with balance scores.

*Interpretation* Individuals with visual impairment adopt precautionary gait in
 dim lighting conditions. This does not always result in improvements in the
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- 72 Key words: lighting, kinematics, temporal-spatial parameters, clearance,
- Accepticonnantocarb 73 vision, clearance variability

#### 74 Introduction

Falls are a common cause of morbidity, mortality and loss of function in older people [1]. Stair-related falls account for approximately one fifth to one third of accidental falls of older people at home [2, 3]. Falls on stairs is a leading cause of accidental death, accounting for 10% of fall-related mortality, approximately 80% of which are of individuals aged 65 or over [4].

The presence of age-related diseases and disabilities, as well as the physiological changes caused by ageing that affect sensory and motor functions, put older people at a higher risk of falling than their adolescent counterparts. The deterioration of the visual system is one such change that has been related to an increased risk of falls in this population. Poor vision was found to be an independent risk factor [5, 6], approximately doubling the risk of falling of older persons [6-8].

In addition to intrinsic risk factors, environmental hazards are another leading cause of falls in older people, accounting for approximately one-third of reported falls [9]. Studies assessing hazards that lead to falling in the homes of older people have identified inadequate lighting to be one of the main factors leading to a fall incidence [10-12]. Few studies have attempted to quantify the link between the deterioration of vision in older people, poor lighting and the risk of falling.

Previous studies investigating the effects of lighting luminance levels on stair
negotiation have looked at effects on ground reaction forces [13], minimum
foot clearance and clearance variability [14, 15], temporal spatial parameters
[16] and centre-of-mass progression [15]. In low lighting conditions, older

participants were found to have a reduced step length [15] and a decreased
first peak of the vertical ground reaction force in stair descent [13], thus
suggesting an adoption of safer stepping strategies in poor lighting conditions.
However, other studies have not found changes in other movement
parameters when lighting conditions were altered [16].

103 None of the previous studies included participants with known visual 104 impairments. This is particularly important as the association of poor vision 105 and measures of static [17, 18] and dynamic stability [19] is well-documented 106 in the literature. The presence of this risk factor as well as inadequate lighting 107 may result in significant changes in the biomechanical characteristics of stair 108 negotiation, which may help explain any relationship between visual 109 impairment, poor lighting and the increased risk of falls in this population.

The aim of this study was to investigate the effect of lighting illuminance levels on stair negotiation performance in a group of older participants with visual impairments. The study assesses biomechanical parameters associated with risk of falling during stair ascent and descent; clearance and movement variability, as well as parameters related to changes in stepping strategies; joint kinematics, temporal and spatial parameters.

#### 116 Methods

#### 117 Participants

118 The study was reviewed and granted ethical approval by Surrey Research 119 Ethics Committee. A power analysis for a repeated-measures ANOVA design 120 revealed that a minimum of 9 participants are needed to achieve a statistical

power of 0.8 with a significance level of 0.05. The effect size was estimated to
be 0.25 and the correlation amongst repeated measures was estimated to be
0.80 based on the results obtained from a pilot study.

Eleven participants (seven males) with a mean age of 78 (6) years consented 124 to taking part in the study and signed a consent form. Participants were 125 included in the study if they were: 1) aged 60 or over, 2) partially sighted due 126 to macular degeneration or advanced cataract caused by old-age, all patients 127 with macular degeneration had a vision of 6/18 or worse and 3) able to 128 negotiate stairs using a step-over-step strategy. Participants were excluded if 129 they: 1) had a muscular or neurological condition or impairment that affected 130 or limited their gait or 2) had a diagnosed vestibular disorder. In addition, a 131 clinician assessed the participants' lower-limb joints (hip, knee and ankle) 132 133 range of motion, lower-limb muscle power and mobility and used Berg Balance Score (BBS) [20], participants were excluded if they displayed 134 135 reduced balance caused by dizziness. The activities-specific balance confidence scale (ABC) [21] and the stair self-efficacy questionnaire (SSE) 136 [22] were also completed by the participants. Participants also completed 137 questionnaires on the use of the laboratory stairs and the lighting conditions. 138 139 Participants were asked if they thought the stairs were poorly lit and if the 140 stairs were safe to use (see Table S1).

141 Laboratory Setup and Lighting Configurations

A seven-step staircase (tread 300mm, rise 180mm, width 1000mm, pitch 31°)
was constructed from medium density fibre board (MDF). The staircase had a
top landing area of 1500x1000mm, handrails on one side and a wall on the

other, thus simulating a domestic staircase. The walls were painted with
neutral colour paint to simulate a domestic colour scheme.

An array of 4x100W incandescent lamps were used on the top landing of the 147 staircase, a 200W lamp was used at the bottom landing of the stairs in 148 addition to laboratory lights and diffusers (Figure 1A). A dimmer switch control 149 was used to allow adjustment of lighting conditions and a light meter 150 (ISOTECH, England) was used to measure illuminance levels from the top 151 landing. This configuration was used to achieve five lighting conditions; low 152 illuminance 50lx, sub-optimal lighting 100lx, optimal lighting 200lx, increased 153 154 illuminance 300lx and distributed 200lx lighting. The poorest lighting condition used in this study (50lx) was based on the findings of the study by Hill et al 155 (2000), which surveyed 150 older people's households and found that more 156 157 than 60% of these had lighting of 50lx or less during the day [23]. Optimal defined as an illuminance of 200lx based on 158 lighting was the 159 recommendations of Thomas Pocklington Housing Guide [24].

The distributed 200lx lighting condition was achieved with the laboratory lights 160 161 fully on, the top landing light off and the bottom landing of the stairs dimmed, this arrangement achieved illuminance level of 2001x on the top landing. Other 162 163 lighting conditions were achieved using 4x100W incandescent lamps above 164 the top landing and the dimmer switch. Lighting illuminance was measured at the top landing, the illuminance levels - with the exception of the distributed 165 166 lighting condition- typically fell with the lower steps. This was believed to reflect lighting distribution on staircases in domestic environments. 167

168 Data Collection

169 An 8-camera motion capture system (Qualysis, Gothenburg, Sweden) running 170 at 100Hz was used for data capture and the 6 degree-of-freedom marker model was used [25], the model makes use of 25 retroreflective markers to 171 172 track the movement of the lower-limb segments in dynamic trials. These are divided into 3 markers on the pelvis, 4 marker-clusters on the two thigh and 173 two shank segments and 3 marker-clusters on the two foot segments. Prior to 174 dynamic trials, a pointer was used to digitise relevant anatomical landmarks to 175 allow definitions of segmental coordinate frames (femoral and tibial 176 epicondyles and the 2<sup>nd</sup> metatarsal head). In addition, three points at the area 177 of the heel and three points at the area of the toes were digitised to cover the 178 179 areas of the foot likely to be closest to the stair edge (see Figure S1). The 180 biomechanical model was used to redefine the positions of these points virtually using their relative distances to the markers on the foot segment. The 181 minimum straight-line distance between the stair edge and any one of these 182 points was used for foot clearance measurements [14]. 183

184 Participants were allowed to ascend and descend the staircase before data collection to familiarise themselves with the laboratory set up. Following 185 familiarisation, participants were asked to ascend and descend the staircase 186 187 using a self-selected speed without the use of handrails. Participants were 188 also instructed to initiate gait using their right foot, this was to ensure that they were clearing and landing on the same steps with their right, consequently the 189 190 gait cycles of the right (and left) limbs of all trials and all participants were comparable. Three sets of ascent/descent trials were collected, each set 191 192 included ascending and descending the staircase under the five lighting conditions. The order of the lighting conditions in each set was randomised 193

using a 1-5 random order generator in Microsoft Excel. This gave a total of 30
motion trials to be used for analysis: 3 trials of ascent and 3 trials of descent
under each lighting condition.

#### 197 Data Analysis

Analysis was completed using Visual3D (C-Motion, Germantown, MD) 198 199 software. The hip joint centre-of-rotation was computed using regression equations [26], the mid-points of the epidondyles and the malleoli markers 200 were used to define the knee and ankle joints centres-of-rotation respectively. 201 Coordinate frames for the pelvis, femurs, tibias and feet were defined and 202 joint rotations were computed using a Cardan sequence of flexion-extension, 203 204 abduction-adduction and internal-external rotation for the hip, knee and ankle joints [25]. Gait events were identified using an algorithm [27] implemented in 205 206 Visual3D that makes use of kinematic data. The gait events were adjusted manually when they were identified incorrectly to be in the middle of stance or 207 swing. In which case the events were visually created using the marker data 208 and when the anterior-posterior position of the foot markers indicated an initial 209 210 contact or a foot off. Temporal and spatial gait parameters, clearance and clearance variability were also computed. Clearance was the absolute 211 212 minimum distance between the digitised points on the foot and the stair edge [14]. This position may be different between trials and steps, however, it was 213 214 always one of the toe digitised positions in ascent and one of the heel 215 digitised positions in descent. Clearance variability was the standard deviation between the clearance values from the three trials. 216

217 Analysis was completed for the right side of all participants. In ascent, the 218 right foot initiates gait from the bottom landing of the staircase and lands on the 1<sup>st</sup>, 3<sup>rd</sup>, 5<sup>th</sup> and the top landing of the staircase (Figure 1A). In descent, 219 the right foot initiates gait from the top landing and lands on the 6<sup>th</sup>, 4<sup>th</sup>, 2<sup>nd</sup> 220 and bottom landing of the staircase. The first and last gait cycles were not 221 included in the analysis because the quality of the data was compromised at 222 the top and bottom of the staircase as they were at the extremes of the 223 calibrated capture volume. Table 1 shows the clearance and clearance 224 variability computed for stair ascent and descent. Note that in each gait cycle, 225 the foot clears two step edges before landing. For example, for a right foot 226 gait cycle in ascent initiated at the first step, the foot would have to clear the 227 2<sup>nd</sup> step and the 3<sup>rd</sup> step edge before landing on the 3<sup>rd</sup> step. 228

229 The mean values obtained from the three repeat trials were used in the statistical analysis. Two-factor repeated-measures ANOVA tests were used to 230 231 investigate differences in clearance and clearance variability, the two factors were the lighting condition and the cleared step number. This was completed 232 separately for stair ascent and descent. Finally, repeated-measures ANOVA 233 tests were also used to investigate differences in maximum, minimum and 234 range of joint rotations and temporal and spatial parameters between the 235 236 lighting conditions and the significance was set at p=0.05. Where significant 237 differences were found, a posthoc test with Bonferroni correction was carried out to find where the differences lay. Because of the repeated design, partial 238 eta squared is reported as an indication of the effect size, where 0.01, 0.06 239 240 and 0.14 indicate small, medium and large effect sizes respectively [28].

241 **Results** 

#### 242 Participants

243 The participants had a mean score of 51 (6) on the BBS out of a maximum of 56. Participants also had a mean score of 84 (17) on the ABC scale and a 244 mean score of 74 (18) on the SSE questionnaire; where 100 indicates 245 complete confidence. All participants except one were able to ascend and 246 descend the stairs without using the handrails. The participant that used the 247 handrails was not relying on the handrails for stability and therefore was 248 included in the analysis. All participants had a good range-of-motion and 249 muscle power in the lower-limb (≥4/5 Oxford Scale). One participant had a 250 251 reduced range-of-motion and muscle power (3/5 Oxford scale) in the eversion of the right ankle and another participant was using two sticks to balance. A 252 table showing the patients' information, visual and balance assessments and 253 254 scores in questionnaires have been included as a supplementary data file (see Table S2). 255

All but one of the participants agreed or strongly agreed with the statement 256 that the stairs were poorly lit under the 50lx conditions whilst only one 257 258 participant agreed with this statement under the 200lx distributed lighting condition. Similarly, four participants disagreed with the statement that the 259 260 stairs are safe to use under the 50lx condition compared to a single 261 participant under the 100lx, 200lx and 200lx distributed lighting conditions, 262 and no participants agreed with this statement under the 300lx lighting 263 condition. A summary of the responses to the questions is shown in Table S1.

264 Clearance and Clearance Variability

Table 1 shows the mean and standard deviations for clearance and clearance variability of the first and second cleared steps in ascent and descent. The results show that there was no significant difference in clearance and clearance variability between the different lighting conditions in ascent (p=0.129 and p=0.344 respectively) and in descent (p=0.108 and 0.542 respectively).

In ascent, the mean clearance is generally higher under 50lx lighting with 271 means of 75mm for the first cleared step and 44mm for the second cleared 272 step and lowest under 200lx distributed lighting with means of 68.5mm and 273 274 42.5mm. This difference in the mean values appears to be influenced by the results of three participants, thus suggesting that they adopted a 275 precautionary measure when the lighting condition was poor by increasing 276 277 clearance. However, this trend was not seen with the other participants, thus the difference was not found to be statistically significant. 278

In descent, there is a trend suggesting an increase in clearance in improved lighting conditions compared to lower lighting conditions. This can be particularly seen in the steps further away from the source of light (S5 and S6), where for example, the clearance is 77mm and 50mm under 200lx distributed lighting compared to 70mm and 48mm for the 50lx. This however, did not reach statistical significance (p=0.108).

285 Temporal and Spatial Parameters

Table 2 shows the mean values for the temporal and spatial parameters in the five lighting conditions and the results of the statistical tests. The results show that there were no significant differences in any of the temporal and spatial

289 parameters in ascent. In descent, differences were found in speed (p<0.001), 290 cadence (p<0.001), cycle time (p=0.006), stance time (p<0.001) and right step time (p=0.011). The results of the posthoc statistical test showed that most of 291 292 the significant differences were found between 50lx and 300lx and 200lx distributed lighting. Participants had lower speed, lower cadence, longer cycle 293 time and longer stance time in 50lx illuminance level compared to 300lx and 294 2001x distributed lighting. Significant differences in cadence were also found 295 between 50lx and 200lx; where participants had a lower cadence in 50lx 296 297 illuminance level.

298 Kinematics

The mean hip, knee and ankle sagittal plane angles for ascent and descent for the 50lx lighting condition are shown in Figure 2. Table 3 shows the means and standard deviations of the maximum, minimum and range of hip, knee and ankle rotations in stair ascent and descent for all lighting conditions.

Differences were only found in the minimum hip angle in ascent (p=0.03). The posthoc test with Bonferroni correction revealed that the 200lx level had a significantly greater minimum hip angle compared to the 300lx during ascent (p=0.017).

#### 307 Discussion

The study presents descriptions of the temporal-spatial parameters and lowerlimb kinematics during stair ascent and descent in a group of older individuals with visual impairment under different lighting conditions. The results of the study show that lighting had an effect on the temporal parameters in stair

312 descent, participants had a lower speed and cadence and an increased cycle 313 and stance times. On the other hand, in ascent, cadence and speed were comparable across lighting conditions. Lighting had an effect on the minimum 314 315 hip angle during stair ascent indicating a possible change in movement strategy under different lighting conditions. However, this change was small 316 and did not result in statistically significant differences in clearance or 317 clearance variability in stair ascent and descent. There was also no difference 318 319 in other hip, knee and ankle kinematic parameters in ascent and descent. 320 Previous studies investigating the effect of lighting on stair negotiation have reported the biomechanical parameters in descent only [14, 15]. Interestingly, 321 322 the temporal changes seen in descent due to lighting found in this study are 323 not seen in ascent. This is probably because ascent requires more effort than descent and participants were already negotiating the stairs in lower speeds 324 and cadence in ascent. 325

The results are largely in agreement with those of previous studies that investigated stair negotiation in a group of older people [14, 15]. Hamel et al (2005) and Zietz et al (2011) also found no effect of changing lighting illuminance on clearance in groups of older participants.

Zietz et al (2011) found that different stepping strategies were used by older participants with balance problems compared to older participants with higher balance scores; older participants with compromised balance were found to have reduced clearance and to adjust to differences in stair edge contrast differently to the other older group. Since the primary focus of this study was to focus on patients with visual impairments, no attempts were made to subdivide the participants according to their balance scores. Interestingly, the

337 mean BBS and SSE scores and mean speed found in this study are closer to the scores of the group of participants with compromised balance in the study 338 by Zietz et al (2011). However, the group in this study included a combination 339 340 of participants with low and high balance scores as evidenced by the high standard deviations. This difference in participants' balance and confidence in 341 negotiating steps could explain why only some of the participants in this study 342 were able to adapt to the reduced lighting by increasing their clearance. In 343 order to confirm this suggested role of balance and confidence in movement. 344 345 a Pearson's correlation test was carried out between clearance in the dim lighting condition (50lx) and the BBS, SSE and ABC scores, the results reveal 346 a moderate correlation between all three scores and minimum clearance in 347 descent, this correlation is significant for the SSE (r=0.664,p=0.026) and ABC 348 349 (r=0.620, p=0.042) scores. The results of this analysis reveals that the parameters used to assess safety when negotiating steps, such as clearance, 350 351 are likely to be associated with the individual's overall ability to balance, this is also in line with the findings of Zietz et al (2011). 352

In addition to clearance, previous studies have found clearance variability and variability in other gait measures to be important in the assessment of the risk of falling [14, 29]. Lighting was not found to have an effect on this measure in this study.

The most evident changes to gait characteristics were those seen in temporal parameters during stair descent, where participants reduced their speed as a precautionary measure when descending in dimmer lighting conditions. These adaptations have previously been linked to fear of falling [29] and do not necessarily reduce the risk of falling. This is also evident by the absence of a

362 statistically significant difference in other parameters linked with the risk of363 falling, such as clearance and gait variability as previously discussed.

Generally, lower-limb kinematics were not found to change with different lighting conditions. The failure to promote safe stepping by improving riskrelated parameters such as clearance are probably due to the inability of the participants to control or alter their movements during ascent and descent; this may be compounded by other factors that affect motor and sensory functions in this population.

This study included patients with visual impairment due to old-age, however, it 370 should be acknowledged that the underlying cause for visual impairment of 371 372 the participants was either macular degeneration or cataract. The visual disturbances associated with these two conditions are different and therefore 373 374 it may be argued that patients with these conditions adapt differently to low levels of lighting. However, the focus of this study was to include participants 375 with severe visual impairment, and all patients included here were with severe 376 visual impairment as assessed by the visual acquity scores. Contrast 377 378 sensitivity was not assessed in this study because it was not believed to be of use in this population. This is because, contrast sensitivity becomes a less 379 380 powerful measure as the vision gets weaker, especially in patients with 381 macular degeneration. In patients with cataract, contrast sensitivity is important in performing activities of daily living in the face of an otherwise 382 383 reasonable visual acuity i.e. early cataract, however, this was not the population of interest. 384

385 The lighting conditions tested in this study covers a wide range from a typical 386 poorly lit domestic staircase to an optimised distributed lighting condition unlikely to be available in home environments. However, one of the limitations 387 388 of this study is that it does not test negotiation of steps in the dark. Previous studies indicate that a number of older people do not use lighting at night [30], 389 the influence of this behavioural risk factor has not been assessed in this 390 study. One reason very low lighting illuminance was not measured in this 391 392 study is because the participants here had visual impairments and thus were 393 more likely to use lighting when available. The focus of this study was therefore to assess the spectrum of different lighting conditions that are likely 394 to be available in domestic staircases. 395

In addition to visual input, previous studies have identified kinaesthetic feedback as an important factor in successful negotiation of stairs [31]. The sensory function of the participants included in this study was not tested, and it may be that unidentified losses in their proprioception have also impeded them from using safer stepping strategies. Losses in other muscle strength and flexibility are also likely to play a role in movement control in this population [32].

The experimental setup adopted here could have been affected by habituation, meaning that the participants may have been habituated with the laboratory setup towards the end of the data collection session. To reduce the effect of habituation, the participants were given time to familiarise themselves with the staircase and laboratory surrounding before data collection. A randomisation process was also used to change the test condition after each ascent/descent trial as described in the methods. The study is also limited by

410 the small sample size. The repeated design used here as well as the high 411 correlation between the measurements allowed the investigation of the effect 412 of lighting. However, the study would have benefitted from a larger sample 413 size to confirm the results reported in this study.

Future studies should focus on testing multi-component interventions that also address losses in sensory function, muscle strength and balance with a significantly greater number of participants to avoid the limitations encountered here.

#### 418 **Conclusion**

419 The results of this study show that participants with visual impairment are likely to walk more slowly in dimmer lighting conditions, suggesting an 420 increased fear of falling. However, this precautionary behaviour does not 421 necessarily lead to an increase in step clearance. Minimum clearance in 422 negotiating steps in the dim lighting conditions was found to have a moderate 423 positive correlation with the balance scores of this group, suggesting that 424 425 ability to balance plays a role in negotiating steps safely and thus in the ability to adapt stepping strategies under different lighting conditions. 426

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#### Acknowledgments 428

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- Figure 1: A- Showing 7-step staircase in the Movement Laboratory and the
- 682 lighting configuration. B Participant with reflective markers attached to the
- 683 lower-limb and pelvis descending the staircase.

684

- Figure 2: Rotations of the hip, knee and ankle rotation angles in the sagittal
- 686 plane during one cycle of stair ascent and stair descent under the low-
- 687 illuminance lighting condition (50lx).

- Figure S1: Showing the digitised positions in the heel and toe areas of the
- 690 shoe used in the computation of clearance. The points cover the areas of the
- 691 toe and heel closest to the stair edge in ascend and descend.



В



Table 1: Clearance and clearance variability for the cleared steps under the five lighting conditions in stair ascent and descent. The reported p-values are of the two-factor repeated ANOVA tests comparing clearance and clearance variability under the 5 lighting conditions for the 4 steps in ascent and in the 4 steps in descent, significance level is set at p=0.05.

ASCENT										
	50lx	50lx 100lx 200lx 300		300lx	x 200lx		Lighting		ıg*step	
Lignung	Mean (SD)	Mean (SD)	Mean (SD)	Mean (SD)	aistributea	p-value	$\eta_p^2$	p-	$\eta_p^2$	
Steps					Mean (SD)			value		
			Clearance (mm)		0	0.129	0.193	0.726	0.045	
1 <sup>st</sup> cleared										
step	75 (34)	67 (26)	70 (22)	69 (20)	65 (25)					
S2	75 (29)	66 (25)	67 (20)	66 (22)	66 (21)					
<b>S4</b>										
2 <sup>nd</sup> cleared						-				
step	45 (16)	42 (12)	43 (14)	42 (10)	38 (13)					
S3	43 (17)	39 (11)	42 (13)	38 (12)	37 (11)					
S5										
		Clear	rance Variability	(mm)		0.344	0.093	0.533	0.068	
1 <sup>st</sup> cleared						-				
step	17 (22)	12 (6)	9 (4)	8 (6)	11 (6)					
S2	17 (23)	11 (4)	11 (8)	7 (5)	9 (6)					
S4										
					1					
		V							3	
	$\mathbf{O}$	)								

2 <sup>nd</sup> cleared									
step									
	10 (16)	9 (4)	9 (9)	6 (5)	7 (4)				
<b>S</b> 3	10(12)	6 (F)	0 (0)	E (E)	F (2)				
SE	10(12)	0(5)	0 (0)	5 (5)	5 (2)				
33									
			Clearance (mm)			0.108	0.169	0.404	0.093
1st cloarad									
1 <sup>st</sup> cleared									
step	70 (27)	73 (29)	74 (25)	75 (30)	77 (26)				
<b>S6</b>									
	71 (29)	70 (33)	74 (30)	71 (34)	76 (31)				
<b>S4</b>									
2nd cloared						-			
2 <sup>nu</sup> cleai eu									
step	48 (28)	46 (26)	45 (22)	50 (22)	50 (19)				
<b>S5</b>									
	48 (25)	44 (24)	44 (26)	46 (23)	48 (24)				
<b>S</b> 3									
		Clas		0542	0.050	0.105	0.164		
		Clea	Talle variability	(mm)		0.342	0.039	0.105	0.104
1 <sup>st</sup> cleared									
step									
_	12 (6)	8 (5)	11 (6)	11 (8)	11 (7)				
<b>S</b> 6	9 (3)	8 (5)	9 (4)	8 (0)	7 (6)				
\$4	5 (3)	0(3)	(H)	0())	7 (0)				
51									
			1	1	1	1	•	1	1
									-
									3

2 <sup>nd</sup> cleared step S5 S3	11 (8) 9 (7)	9 (5) 11 (5)	6 (3) 5 (4)	9 (9) 6 (8)	9 (5) 10 (5)		
	0						

ASCENT									
Lighting	Lighting 50lx 100lx 200lx 300lx 200lx distributed Light					hting			
Temporal-	Mean (SD)	Mean (SD)	Mean (SD)	Mean (SD)	Mean (SD)	p-value	$n_{\pi}^2$		
spatial parameters					4		-10		
Speed (m/s)	0.54 (0.10)	0.54 (0.11)	0.54 (0.11)	0.54 (0.11)	0.54 (0.11)	0.807	0.039		
Cadence (steps/min)	91.0 (16.0)	89.6 (15.7)	90.1 (16.5)	90.3 (16.6)	90.8 (16.9)	0.637	0.060		
Cycle time (s)	1.41 (0.33)	1.41 (0.29)	1.42 (0.34)	1.41 (0.31)	1.42 (0.36)	0.959	0.004		
Stance time (s)	0.90 (0.27)	0.90 (0.24)	0.90 (0.26)	0.90 (0.26)	0.92 (0.31)	0.707	0.238		
Swing time (s)	0.49 (0.07)	0.49 (0.07)	0.49 (0.10)	0.49 (0.07)	0.48 (0.08)	0.698	0.052		
Double support time (s)	0.41 (0.22)	0.41 (0.18)	0.41 (0.20)	0.43 (0.21)	0.43 (0.24)	0.309	0.110		
Right step time (s)	0.69 (0.16)	0.70 (0.14)	0.70 (0.18)	0.70 (0.17)	0.70 (0.18)	0.767	0.027		
Stride length (m)	0.73 (0.02)	0.74 (0.03)	0.74 (0.03)	0.73 (0.03)	0.73 (0.03)	0.280	0.117		
Stride width (m)	0.12 (0.04)	0.12 (0.04)	0.13 (0.04)	0.13 (0.04)	0.13 (0.04)	0.492	0.066		
		DESC	CENT						
Speed (m/s)	0.54 (0.14)	0.56 (0.15)	0.56 (0.15)	0.58 (0.15)	0.57 (0.15)	<0.001	0.419		
Cadence (steps/min)	88.6 (21.1)	92.7 (22.5)	93.4 (22.9)	97.4 (22.0)	95.4 (22.6)	<0.001	0.431		
Cycle time (s)	1.49 (0.53)	1.45 (0.52)	1.44 (0.53)	1.37 (0.50)	1.39 (0.51)	0.006	0.409		
Stance time (s)	0.92 (0.35)	0.90 (0.37)	0.90 (0.35)	0.85 (0.33)	0.84 (0.32)	<0.001	0.411		
Swing time (s)	0.59 (0.21)	0.58 (0.20)	0.58 (0.22)	0.55 (0.17)	0.56 (0.18)	0.124	0.185		
Double support time (s)	0.31 (0.15)	0.26 (0.12)	0.27 (0.12)	0.26 (0.11)	0.27 (0.14)	0.140	0.183		
Right step time (s)	0.74 (0.25)	0.71 (0.25)	0.71 (0.27)	0.67(0.22)	0.69 (0.27)	0.011	0.274		
Stride length (m)	0.74 (0.02)	0.74 (0.03)	0.74 (0.04)	0.74 (0.03)	0.73 (0.03)	0.822	0.037		
Stride width (m)	0.14 (0.04)	0.15 (0.05)	0.15 (0.04)	0.15 (0.04)	0.15 (0.04)	0.376	0.098		

Table 2: Temporal and spatial parameters under the five lighting conditions and the p-values of the statistical tests for stair ascent and descent, significance level is set at p=0.05.

	ASCENT								
	Lighting	501x	100lx	2001x	300lx	2001x distributed	Ligh	ting	
Joint		Mean (SD)	p-value	$\eta_p^2$					
Hip	Maximum (°)	75.2 (9.9)	74.7 (10.3)	76.1 (9.8)	75.4 (10.5)	74.3 (9.6)	0.097	0.174	
-	Minimum (°)	13.6 (10.6)	14.8 (11.1)	15.6 (12.1)	13.1 (11.1)	13.9 (10.3)	0.030*	0.297	
	Range (°)	61.6 (5.6)	59.9 (5.0)	60.5 (5.8)	62.2 (5.4)	60.4 (5.0)	0.102	0.172	
Knee	Maximum (°)	101.4 (9.1)	101.6 (9.1)	102.1 (8.3)	101.2 (8.9)	100.6 (10.1)	0.581	0.067	
	Minimum (°)	14.3 (7.6)	14.0 (7.6)	14.7 (6.5)	14.3 (7.4)	14.6 (7.1)	0.925	0.022	
	Range (°)	87.1 (5.8)	87.6 (6.3)	87.4 (6.5)	86.9 (5.1)	86.0 (7.3)	0.486	0.067	
Ankle	Maximum (°)	17.9 (4.8)	17.8 (4.6)	17.5 (3.9)	18.0 (4.7)	18.6 (5.3)	0.663	0.057	
	Minimum (°)	-21.9 (7.5)	-22.3 (8.4)	-22.8 (6.1)	-21.6 (7.0)	-22.3 (7.1)	0.543	0.073	
	Range (°)	39.7 (7.0)	40.2 (6.8)	40.3 (6.5)	39.7 (6.6)	40.9 (7.9)	0.731	0.048	
			DES	CENT					
Hip	Maximum (°)	52.8 (10.1)	51.4 (10.5)	52.1 (9.4)	52.3 (9.9)	51.3 (9.9)	0.087	0.180	
	Minimum (°)	19.8 (9.0)	19.4 (9.4)	20.2 (9.8)	20.3 (8.7)	20.1 (9.0)	0.693	0.053	
	Range (°)	32.9 (4.3)	32.0 (4.9)	31.9 (4.3)	32.0 (3.5)	31.2 (4.1)	0.290	0.116	
Knee	Maximum (°)	101.8 (8.2)	101.2 (7.9)	101.3 (8.0)	101.1 (7.8)	101.0 (7.9)	0.670	0.056	
	Minimum (°)	12.1 (6.2)	11.7 (5.5)	12.4 (4.8)	12.8 (4.6)	12.7 (5.2)	0.209	0.133	
	Range (°)	89.8 (6.0)	89.5 (6.0)	88.9 (5.7)	88.3 (5.6)	88.3 (7.0)	0.317	0.109	
Ankle	Maximum (°)	27.9 (6.5)	28.2 (6.7)	28.4 (6.3)	28.2 (6.1)	28.0 (6.5)	0.620	0.062	
	Minimum (°)	-31.4 (4.4)	-21.8 (4.5)	-31.3 (4.7)	-31.8 (4.1)	-31.4 (4.9)	0.556	0.071	
	Range (°)	59.2 (7.6)	59.9 (7.8)	59.7 (7.8)	60.0 (7.4)	59.4 (8.2)	0.404	0.088	
38									

Table 3: Maximum, minimum and ranges of hip, knee and ankle rotations under the five lighting conditions and the p-values of the statistical tests for stair ascent and descent, significance level is set at p=0.05.

#### Authors Bio

Aliah F Shaheen is a Senior Lecturer in Biomechanics at Brunel University London. Prior to that, she was a Lecturer in the Centre for Biomedical Engineering at the University of Surrey where this work was conducted. Her research interests are in the areas of movement and structural variability and their role in function with applications in upper limb biomechanics, ageing and more recently, animal locomotion.

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#### **Conflict of Interest**

Acception