Robust estimation under error cross section dependence

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HIGHLIGHTS

• Propose a variance estimator for fixed effects and mean group estimators in panels.
• Robust to various forms of serial and cross-sectional dependence in errors.
• Useful in applied work for large N short T panels when little is known about the process generating the errors.
• Shown to be consistent for N going to infinity, with T fixed.

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ABSTRACT

We propose a robust, partial sample estimator for the covariance matrix of the fixed effects and mean group estimators of the slope coefficients in a short T panel data model with group-specific effects and errors that are weakly cross sectionally dependent and serially correlated.

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1. Introduction

Recently, a number of studies have focused on robust estimation of the slope parameters of a regression model where errors are cross sectionally dependent. Variants of the Newey and West (1987) spectral density estimator in time series have been suggested by Conley (1999) and Driscoll and Kraay (1998) in the context of GMM estimators of spatial panels where T is large relative to N (see also Pinkse et al., 2002). More recently, Kelejian and Prucha (2007) have proposed a spatial version of the non-parametric heteroskedasticity–autocorrelation consistent (HAC) estimator introduced by White (1980) for a single cross section regression with spatially correlated errors. This approach has been extended by Moscone and Tosetti (2012) in the context of a panel data model with unobserved fixed effects, where errors are allowed to be both spatially and serially correlated for N and/or T going to infinity. Rather than using an arbitrary measure of distance between units, Bester et al. (2009) have recently suggested to split the sample into groups so that group-level averages are approximately independent, and then use the HAC estimator based on a discrete group-membership metric. However, the validity of this approach relies on the capacity of the researcher to construct groups whose averages are approximately independent. Robust inference with clustered data has also been considered by Ibragimov and Müller (2009), Cameron and Miller (2011), Cameron et al. (2011) and MacKinnon and Webb (2014). Robinson (2007) considers smoothed nonparametric kernel regression estimation. Under this approach, rather than employing mixing conditions, it is assumed that regression errors follow a general linear process representation covering both weak (spatial) dependence as well as dependence at longer ranges. Hence, the author establishes con-
sticity of the Nadaraya–Watson kernel estimate and derives its asymptotic distribution.

In this paper, we propose a partial sample estimator for the covariance matrix of the fixed effects (FE) and mean group (MG) estimators of the slope coefficients in a panel data model with unobserved fixed effects and errors that are weakly cross-sectionally dependent and serially correlated. The idea is approximate the true covariance matrix with a (weighted) average of cross products of regression errors, computed over a subset of n cross sectional units, where n → ∞ as N rises, and n/N → 0.¹ We prove that the suggested partial sample estimator tends to the true covariance matrix calculated over the partial sample observations, for N going to infinity, with T fixed. A small Monte Carlo exercise reported in the paper shows that this approach is quite robust to various forms of weak cross sectional dependence, when N is large. The proposed method can be very useful for robust estimation in the context of micro-dataset where N is very large and there is little knowledge on the process generating cross sectional dependence.

2. The econometric framework

Consider the panel data model

\[ y_{it} = \alpha_i + \beta' x_{it} + \epsilon_{it}, \quad i = 1, 2, \ldots, N; \quad t = 1, 2, \ldots, T, \]  

where \( \alpha_i \) are fixed parameters, \( x_{it} \) are strictly exogenous regressors, and \( \epsilon_{it} \) follows the general process:

\[ \epsilon_{it} = \rho_1 \epsilon_{i,t-1} + \rho_2 \epsilon_{i,t-2} + \cdots + \rho_N \epsilon_{i,0}, \]  

where \( \rho_j \) are (unknown) elements, possibly function of a smaller set of coefficients, of a \( N \times N \) non-stochastic matrix, \( R = (r_1, r_2, \ldots, r_N)' \), with \( r_1 = (\rho_1, \rho_2, \ldots, \rho_N)' \), and \( E(\epsilon_{i,0}) = 0 \), but can be serially correlated. We make the following assumptions on the error term and regressors.

Assumption 1. \( \epsilon_{it} \) are independently distributed across i, with \( E(\epsilon_{i,t}) = 0, E(\epsilon_{i,t}^2) < \infty \) and \( E(\epsilon_{i,t} \epsilon_{j,t}') = \Omega \), with \( \Omega \) being a finite, positive definite T-dimensional matrix with (t,s)th element, \( \omega_{ts} \).

Assumption 2. \( \max_{1 \leq t \leq N} \sum_{j=1}^{N} |r_j| < \infty; \ max_{1 \leq t \leq N} \sum_{j=1}^{N} |r_j| < \infty. \)

Assumption 3. \( x_{it} \) has finite elements, and \( \lim_{N \rightarrow \infty} T \rightarrow \infty \) \( \sum_{t=1}^{N} X_i \) \( X_i' \) finite and non-singular, with \( \tilde{X}_i = MX_i, \ \tilde{X}_i = (X_{1t}, X_{2t}, \ldots, X_{Tt})' \), \( M = I - \frac{1}{T} (1_{T} 1_{T}')^{-1} 1_{T} 1_{T}' \).

Under Assumptions 1–2, 0 \( \leq |E(\epsilon_{i,t} \epsilon_{j,t}')| = \sum_{j=1}^{N} \sum_{h=1}^{N} \rho_{ih} \rho_{jh} |r_{ih} r_{jh}'| < \infty \), for all i, j, t, s, and the covariance matrix of \( \epsilon_{i,t} = (\epsilon_{i,t}, \epsilon_{i,t+1}, \ldots, \epsilon_{i,N-1})' \), for each t, have absolute summable elements, i.e., \( \sum_{j=1}^{N} |E(\epsilon_{i,t} \epsilon_{j,t}')| \leq \sum_{j=1}^{N} |r_{ih} r_{jh}'| < \infty \), thus carrying weak cross section dependence. A large variety of models can be cast in this framework, for example, the spatial autoregressive process having AR or MA errors, or a common factor structure with weak factors.

3. Robust estimation

The FE and MG estimators of \( \beta \) in Eq. (1) are:

\[
\hat{\beta}_p = \left( \sum_{j=1}^{N} \tilde{X}_j \tilde{X}_j' \right)^{-1} \sum_{j=1}^{N} \tilde{X}_j \tilde{y}_j, \]  

\[
\hat{\beta}_{MG} = \frac{1}{N} \sum_{j=1}^{N} \tilde{\beta}_j, \]  

with \( \tilde{y}_j = My_j \) and \( \tilde{\beta}_j = (\tilde{X}_j \tilde{X}_j')^{-1} \tilde{X}_j \tilde{y}_j \). Under Assumptions 1–3, it is easy to show that, as N tends to infinity and for T fixed, \( \sqrt{N} (\hat{\beta}_p - \beta) \overset{P}{\rightarrow} N(0, \Sigma_p) \), and \( \sqrt{N} (\hat{\beta}_{MG} - \beta) \overset{P}{\rightarrow} N(0, \Sigma_{MG}) \), where (see Hansen, 2007; Pesaran and Tosetti, 2011)

\[
\Sigma_p = Q^{-1} \Psi Q^{-1}, \]  

\[
\Sigma_{MG} = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{j=1}^{N} \sum_{t=1}^{T} w_{it} w_{jt}^* \omega_{tt} r_t r_j, \]  

where \( Q = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{j=1}^{N} X_i X_j' \), \( w_{it} \) is the ith column of \( W_i = (X_i X_i')^{-1} X_i' \), \( \omega_{tt} = \text{diag} (\omega_{1t}, \omega_{2t}, \ldots, \omega_{Nt}) \), and

\[
\Psi = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \tilde{X}_i \tilde{X}_j' w_{it}^* \omega_{tt} r_t r_j. \]  

Note that \( \Sigma_{MG} \) and \( \Sigma_p \) depend on the nuisance parameters in the matrices \( R \) and \( \omega_{tt} \). Let \( n/N \) be such that \( n \rightarrow \infty \) and \( n/N \rightarrow 0 \), with \( n/N \rightarrow 0 \), (8) reduces to the Arellano (1987) cluster-robust variance estimator; while the variance estimator (9) is based on the robust estimator considered in Pesaran and Smith (1995), and Pesaran (2006). The following theorem shows that the suggested partial sample estimators (8)–(9) tend to a positive definite matrix, which is the true covariance matrix computed using the partial sample observations. Such matrix is a fraction of the true variance based on N observations (see Appendix for a proof).

Theorem 1. Let \( \hat{\Sigma}_p \) and \( \hat{\Sigma}_{MG} \) given by (8) and (9), respectively, and let \( n \) be such that \( n \rightarrow \infty \), and \( n/N \rightarrow 0 \). Then under 1–3, for fixed T,

\[
\psi(n) = \Psi(n) + O_p \left( \frac{1}{\sqrt{n}} \right), \]  

\[
\hat{\Sigma}_{MG} = \hat{\Sigma}_{MG} + O_p \left( \frac{1}{\sqrt{n}} \right), \]  

where \( \psi(n) = \frac{1}{n} \sum_{t=1}^{T} \sum_{s=1}^{T} X_i X_j X_i X_j' \omega_{tt} r_t r_j, \) and \( \hat{\Sigma}_{MG} = \frac{1}{n} \sum_{i=1}^{N} \sum_{j=1}^{N} w_{ij} w_{ij}^* \omega_{tt} r_t r_j. \) Further, for \( n \rightarrow \infty \),

\[
\psi(n) = \frac{n}{N} \Psi(n) + O_p \left( \frac{1}{\sqrt{n}} \right), \]  

\[
\hat{\Sigma}_{MG} = \frac{n}{N} \hat{\Sigma}_{MG} + O_p \left( \frac{1}{\sqrt{n}} \right). \]  

¹ We found a similar idea based on partial sample briefly outlined in Bai (2009), Remark 8, although no formal proof has been provided.
Table 1
Monte Carlo results, FE estimator.

<table>
<thead>
<tr>
<th>N</th>
<th>T</th>
<th>(I): Cluster-robust estimator</th>
<th>(II): Partial sample estimator</th>
<th>(II): Partial sample estimator</th>
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<tr>
<td></td>
<td></td>
<td>$n = N^{0.3}$</td>
<td>$n = N^{0.4}$</td>
<td>$n = N^{0.5}$</td>
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<tr>
<td></td>
<td></td>
<td>Size</td>
<td>Power</td>
<td>Size</td>
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<td>0.996</td>
<td>0.048</td>
</tr>
<tr>
<td>1000</td>
<td>5</td>
<td>0.049</td>
<td>1.000</td>
<td>0.043</td>
</tr>
<tr>
<td>300</td>
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<td>500</td>
<td>10</td>
<td>0.057</td>
<td>1.000</td>
<td>0.046</td>
</tr>
<tr>
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<td>10</td>
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<td>1.000</td>
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<td>0.921</td>
<td>0.076</td>
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<td>0.986</td>
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<tr>
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<td>0.069</td>
<td>1.000</td>
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<td>0.998</td>
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<td>1.000</td>
<td>0.044</td>
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<tr>
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<td>1.000</td>
<td>0.045</td>
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<tr>
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<td>5</td>
<td>0.144</td>
<td>0.523</td>
<td>0.066</td>
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<tr>
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<td>10</td>
<td>0.148</td>
<td>0.948</td>
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</tr>
</tbody>
</table>

Note: The size and power reported in Column I use the robust estimator for the variance, while those in column (II) use expression (8).

Clearly, for a small $n$ the variance estimators converge fast to their true counterparts, but these only estimate a small fraction of the total variance. On the contrary, a large $n$ implies slower convergence but a larger estimated fraction of the total variance. Using the above results, the Student’s t-statistics for the unknown parameter associated to the $\ell$th regressor using the FE and MG estimators and their partial sample variance estimator are:

\[ t_{p,\ell} = \frac{\sqrt{n/N} \left( \hat{\beta}_{p,\ell} - \beta_\ell \right)}{\sqrt{\sum_{i=1}^{n} (\hat{\epsilon}_{i,\ell}^2)}} \]

\[ t_{MC,\ell} = \frac{\sqrt{n/N} \left( \hat{\beta}_{MC,\ell} - \beta_\ell \right)}{\sqrt{\sum_{i=1}^{n} (\hat{\epsilon}_{i,\ell}^2)}} \]

\[ \ell = 1, 2, \ldots, k. \]

4. Monte Carlo experiments

Suppose $y_{it}$ for $i = 1, 2, \ldots, N$ and $t = -49, 0, 1, \ldots, T$, are generated by the following panel data model

\[ y_{it} = \alpha_i + \beta x_{it} + u_{it}, \]

where $\beta = 1$, and the parameters $\alpha_i$ are generated as $\alpha_i \sim IIDN(1, 1)$, $i = 1, 2, \ldots, N$ and do not change across replications. The regressor is generated as:

\[ x_{it} = \alpha_i + 0.4x_{i,t-1} + u_{it}, \]

for $i = 1, 2, \ldots, N$, $t = -49, 0, 1, \ldots, T$,

\[ u_{it} = 0.4 \sum_{j=1}^{N} s_{ij} y_{jt} + \epsilon_{it}, \]

where $\epsilon_{it} \sim N(0, \sigma_{it}^2)$, $\sigma_{it}^2 \sim IIDU(0.5, 1.5)$, for $i = 1, 2, \ldots, N$. As for the individual-specific errors, $e_{it}$, we assume the following spatio-temporal process:

\[ e_{it} = 0.4e_{i,t-1} + w_{it}, \]

for $i = 1, 2, \ldots, N$, $t = -49, 0, 1, \ldots, T$, (15)

\[ w_{it} = \delta_i \sum_{j=1}^{N} s_{ij} y_{jt} + \epsilon_{it} \]

\[ \epsilon_{it} \sim N(0, \sigma_{it}^2), \sigma_{it}^2 \sim IIDU(0.5, 1.5), \]

for $i = 1, 2, \ldots, N$, (17)

where $s_{ij}$ are elements of a $N \times N$, time-invariant, row-normalised, 2nd order regular lattice. The first 50 observations are discarded. We carry three experiments. In Experiment 1 we consider a pure temporal process and set $\delta_i = 0$. In Experiment 2 we assume a moderate degree of spatial correlation, $\delta_i \sim IIDU(0.2, 0.4)$, while in Experiment 3 we consider a more sizeable degree of spatial dependence, setting $\delta_i \sim IIDU(0.7, 0.9)$. The Arellano (1987) cluster-robust estimator and the robust estimator considered in Pesaran and Smith (1995) deliver correct inference under Experiment 1, while they are biased under Experiments 2 and 3. The number of replications is set to 1000, experiments are carried for $N = 300, 500, 1000$, and $T = 5, 10$, and we try three alternative choices of $n$, by setting $n = N^{0.3}, N^{0.4}, N^{0.5}$.

4.1. Results

We report size and power for both FE and MG estimators using (8) and (9), for various choices of $n$. For a comparison, we also report the Arellano (1987) cluster-robust estimator and the robust estimator considered in Pesaran and Smith (1995). The nominal size is set to 5%, while the power of the various tests is computed under the alternative $H_1 : \beta = 0.90$. Results reported in Tables 1 and 2 show that the proposed estimators work well.

Appendix

Lemma 1. Consider the process $e_{it}$ in (2). Under Assumptions 1–2, for fixed $T$,

\[ E \left( \frac{1}{n} \sum_{i,j=1}^{n} \sum_{t=1}^{T} e_{it} e_{jt} \right) = O(1), \]

and

\[ \text{Var} \left( \frac{1}{n} \sum_{i,j=1}^{n} e_{it} e_{jt} \right) = O \left( \frac{1}{n} \right). \]

(18)

\[ 2 \] We have omitted to report Bias and RMSE of Pooled and MG estimators but these are available upon request.
Further, we have

\[
\frac{1}{N} \sum_{i=1}^{n} \sum_{j=1}^{T} \sum_{t=1}^{n} e_{it} e_{jt} = O_p \left( \frac{n}{N} \right). \tag{19}
\]

**Proof.** To prove (18), we note that:

\[
0 < \frac{1}{N} \sum_{i=1}^{n} \sum_{j=1}^{T} e_{it} e_{jt} = \frac{1}{n} \left[ \sum_{i=1}^{T} \left( \sum_{j=1}^{n} e_{it} e_{jt} \right) \right] \leq T \frac{1}{n} \sum_{i=1}^{T} \left( \sum_{j=1}^{n} e_{it} e_{jt} \right)^2 = T \frac{1}{n} \sum_{i=1}^{T} e_{i}^T R R_{i},
\]

where elements in \( e_{it} = (e_{i1}, e_{i2}, \ldots, e_{iN})' \) are distributed independently across \( i \) with mean zero, finite variance and finite fourth-order moments, and the matrix \( A = R R \) has absolute summable row and column sums. It follows that we can apply Lemma 2 in Kelejian and Prucha (1999) for \( \sum_{i=1}^{T} e_{i}^T A e_{i} \), \( t = 1, 2, \ldots, T \), which implies (18). As for (19), let \( 1_{[1 \leq i \leq n]} \) be an indicator function equal to 1 if \( i \leq n \), and zero otherwise. Noting that \( E \left( 1_{[1 \leq n]} \right) = \frac{n}{N} \) and \( \text{Var} \left( 1_{[1 \leq n]} \right) = \frac{n}{N} \left( 1 - \frac{n}{N} \right) \), it follows that

\[
\frac{1}{N} \sum_{i=1}^{n} \sum_{j=1}^{T} \sum_{t=1}^{n} e_{it} e_{jt} = \frac{1}{N} \sum_{i=1}^{n} \sum_{j=1}^{T} \sum_{t=1}^{n} e_{it} e_{jt} 1_{[1 \leq i \leq n]} = O_p \left( \frac{n}{N} \right). \]  

**Proof of Theorem 1.** We first prove the theorem for \( \hat{\Sigma}_{MG} \). Consider

\[
\hat{\beta}_i \sim \tilde{\beta}_{MG} = W_i \tilde{y}_i - \frac{1}{N} \sum_{k=1}^{N} W_k \tilde{y}_k = W_i \tilde{e}_i - \frac{1}{N} \sum_{k=1}^{N} W_k \tilde{e}_k.
\]

and noting that \( W_i \tilde{e}_i = W_i e_i \), we have:

\[
\hat{\Sigma}_{MG}^{(n)} = \frac{1}{n} \sum_{i,j=1}^{n} (W_i e_i - \frac{1}{N} \sum_{k=1}^{N} W_k e_k) (W_j e_j - \frac{1}{N} \sum_{k=1}^{N} W_k e_k) + \frac{1}{N} \sum_{i,j=1}^{n} W_i e_i e_i W_j.
\]

Using (18) we also have

\[
\text{Var} \left( \frac{1}{n} \sum_{i=1}^{n} W_i e_i e_i W_j \right) = O \left( \frac{1}{n} \right), \tag{20}
\]

**Note:** The size and power reported in Column I use the Pesaran and Smith (1995) robust estimator for the variance, while those in Column II use expression (9).

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Table 2

Monte Carlo results, Mean Group estimator.

<table>
<thead>
<tr>
<th>( N )</th>
<th>( T )</th>
<th>( n = N^{0.3} )</th>
<th>( n = N^{0.4} )</th>
<th>( n = N^{0.5} )</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Power</td>
<td>Power</td>
<td>Power</td>
</tr>
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<tr>
<td>500</td>
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</tr>
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<td>1000</td>
<td>10</td>
<td>0.050 0.942</td>
<td>0.041 0.390</td>
<td>0.048 0.506</td>
</tr>
</tbody>
</table>

Experiment 1 \( \delta_i = 0 \)

Experiment 2 \( \delta_i \sim \text{i.i.d.}(0.2, 0.4) \)

Experiment 3 \( \delta_i \sim \text{i.i.d.}(0.7, 0.9) \)

---

3 It is interesting to observe that for \( n = N \) we have

\[
\hat{\Sigma}_{MG}^{(n)} = \frac{1}{N} \sum_{i=1}^{n} W_i e_i e_i W_j - \frac{1}{N} \sum_{i=1}^{n} W_i e_i e_i W_j = \frac{1}{N} \sum_{i=1}^{n} W_i e_i e_i W_j \]

Hence, using all observations would yield an estimator that collapses to zero.
which implies (12). To prove (14), note that
\[ \sum_{MG}^{(n)} = \frac{1}{n} \sum_{i,j=1}^{T} w_{ij} r_i r_j \omega_{lj}, \]

having mean
\[ \frac{N}{N^2} \sum_{j=1}^{T} \sum_{i=1}^{T} w_{ij} w_{ij} r_i r_j \omega_{lj} = \frac{N}{N^2} \sum_{MG}^{(N)} \]

and variance
\[ \frac{1}{N^2} \sum_{j=1}^{T} \sum_{i=1}^{T} w_{ij} w_{ij} w_{ij} w_{ij} (r_i r_j \omega_{lj})^2 \left( 1 - \frac{n}{N} \right)^2 = O \left( \frac{N}{N^2} \right). \]

It follows that, for large \( N \), \( \sum_{MG}^{(n)} \approx \frac{N}{N^2} \sum_{MG}^{(N)} \). Results (11) and (13) can be proved using a similar line of reasoning as above, by noting that
\[ \hat{\varepsilon}_i = \tilde{\varepsilon}_i + \bar{X}_i (\beta - \beta_c) = \tilde{\varepsilon}_i - \frac{1}{N} \bar{X}_i \sum_{k=1}^{N} Z_k \tilde{\varepsilon}_k, \]
where \( Z_k = \bar{X}_k Q_N^{-1} < K < \infty \), and substituting it in the expression for \( \psi^{(n)} \).

References


