VARIATIONAL INEQUALITIES
AND APPROXIMATION
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## A B S T R A C T

The existence and uniqueness of the solution of a variational inequality is considered, and methods of approximation of the solution are given.

Some elementary theorems concerning bilinear forms and antimonotone operators are given in the appendix.

Let H be a real Hilbert Space with its dual H', whose inner product and norm are denoted by $((\cdot))$ and $\|\cdot\|$ respectively. The pairing between $f \in H^{\prime}$ and $u \in H$ is denoted by ( $f, u$ ). Let $F^{\prime}$ be the Frechet differential of a nonlinear functional $F$ on a closed convex set M in H .

Consider also a coercive continuous bilinear form $\mathrm{a}(\mathrm{u}, \mathrm{v})$ on H , i,e. there exists constants $\alpha>0, \beta>0$ such that

$$
\begin{array}{ll}
a(v, v) \geq \alpha\|v\|^{2} & \text { for all } v \in H \\
|a(u, v)| \leq \beta\|u\|\|v\| & \text { for all } u, v \in H \tag{2}
\end{array}
$$

Furthermore let F be a given element of $\mathrm{H}^{\prime}$. We now consider a functional $\mathrm{I}[\mathrm{v}]$ defined by

$$
I[v]=a(v, v)-2 F(v) \quad \text { for all } v \in H
$$

Many mathematical problems either arise or can be formulated in this form. Here one seeks to minimize the functional I[v] over a whole space $H$ or on a convex set $M$ in $H$. It is well-known [ 1] that if $F$ is a linear functional, then the element $u$ which minimizes I [v] on M is given by

$$
\begin{equation*}
a(u, v-u) \geq(F, v-u) \quad \text { for all } v \in M \tag{3}
\end{equation*}
$$

For a nonlinear Frechet differentiable functional F, it was shown [3] that the minimum of the functional $I[v]$ on $M$ is given by $u \in M$ such that

$$
\begin{equation*}
a(u, v-u) \geq\left(F^{\prime}(u), v-u\right) \quad \text { for all } v \in M \tag{4}
\end{equation*}
$$

Such type of inequalities are known as variational inequalities [1]. Lions-Stampacchia. [1] have studied the existence of a unique solution of (3). The motivation for this report is to show that under certain conditions there does exist a unique solution of a more general variational inequality of which (4) is a special case.

Let us consider the following problem.

## PROBLEM 1

Find $u \in M$ such that

$$
\begin{equation*}
a(u, v-u) \geq(A u, v-u) \quad \text { for all } v \in M \tag{5}
\end{equation*}
$$

where $A$ is a nonlinear operator such than $A u \in H^{\prime}$.
For $M=H$, the inequality (5) is equivalent to finding $u \in H$ such that

$$
a(u, v)=(A u, v) \quad \text { for all } v \in H
$$

and thus our results include the Lax-Milgram lemma as a special case.

## Definition

The operator $T: M \rightarrow H^{\prime}$ is called antimonotone, if

$$
(T u-T v, u-v) \leq 0 \quad \text { for all } u, v \in M,
$$

and is said to be hemicontinuous [4], if for all $u, v \in M$, the mapping $t \in[0,1]$ implies that $(T(u+t(v-u)), u-v)$ is continuous. Furthermore, $T$ is Lipschitz continuous, if there exists a constant $0<Y \leq 1$ such that

$$
\|T u-T v\| \leq \Upsilon\|u-v\| \quad \text { for all } u, v \in M
$$

## Theorem 1.

Let $\mathrm{a}(\mathrm{u}, \mathrm{v})$ be a coercive continuous bilinear form and M
a closed convex subset in $H$. If $A$ is a Lipschitz continuous antimonotone operator with $Y<\alpha$, then there exists a unique $u \in M$ such that (5) holds.

The following lemmas are needed for the proof.

## Lemma 1.

If $A$ is an antimonotone hemicontinuous operator, then $u \in M$ is a solution of (5) if and only if $u$ satisfies

$$
\begin{equation*}
a(u, v-u) \geq(A v, v-u) \quad \text { for all } v \in M \tag{6}
\end{equation*}
$$

## Proof

If for a given $u$ in $M$, (5) holds, then (6) follows by the antimonotonicity of A.

Conversely, suppose (6) holds, then for all $t \in[0,1]$ and
$w \in M, v_{t} \equiv u+t(w-u) \in M$, since $M$ is a convex set. Setting $v=v_{t}$ in (6), we have

$$
a(u, w-u) \geq\left(A v_{t}, w-u\right) \quad \text { for all } w \in M
$$

Now let $t \rightarrow o$. Since $A$ is hemicontinuous, $A v_{t} \rightarrow A u$. It follows that

$$
a(u, w-u) \geq(A u, w-u) \quad \text { for all } w \in M
$$

The map $v \rightarrow a(u, v)$ is linear continuous on $H$, so by Reisz-Frechet theorem, there exists an element $\eta=T u \in H^{\prime}$ such that

$$
\begin{equation*}
a(u, v)=(T u, v) \quad \text { for all } v \in H \tag{7}
\end{equation*}
$$

Let $\wedge$ be a canonical isomorphism from $H^{\prime}$ onto $H$ defined
by

$$
\begin{equation*}
(f, v)=((\wedge f, v)) \quad \text { for all } v \in H, f \in H^{\prime} \tag{8}
\end{equation*}
$$

Then $\|\boldsymbol{\wedge}\|_{H^{\prime}}=\left\|\boldsymbol{\wedge}^{-1}\right\|_{\mathrm{H}}=1$. We note first that by (1),(2) and
(7), it follows that

$$
\begin{array}{lr}
\text { (i) } & \|\mathrm{T}\|
\end{array}
$$

The next lemma is a generalization of a lemma of Lions-Stampacchia [1].

## Lemma 2

$$
\text { Let } \zeta \text { be a number such that } 0<\zeta<\frac{2(\alpha-\gamma)}{\beta^{2}-\gamma^{2}} \quad \text { and } \quad \zeta<\frac{1}{\gamma}
$$

Then there exists a $\theta$ with $0<\theta<1$ such that

$$
\left\|\phi\left(\mathbf{u}_{1}\right)-\phi\left(\mathbf{u}_{2}\right)\right\| \leq\left\|\mathbf{u}_{1}-\mathbf{u}_{2}\right\| \text { for all } \mathbf{u}_{1}, \mathbf{u}_{2} \in \mathbf{H}
$$

where for $u \in H, \phi(u) \in H^{\prime}$ is defined by

$$
\begin{equation*}
(\phi(u), v)=((u, v))-\zeta a(u, v)+\zeta(A u, v) \text { for all } v \in H \tag{9}
\end{equation*}
$$

Proof:
For all $\mathbf{u}_{1}, \mathbf{u}_{2} \in \mathrm{H}$.

$$
\begin{align*}
\left(\phi\left(u_{1}\right)-\phi\left(u_{2}\right), v\right)= & \left(\left(u_{1}-u_{2}, v\right)\right)-\zeta a\left(u_{1}-u_{2}, v\right)+\zeta\left(A u_{1}-A u_{2}, v\right) \text { for all } v \in H \\
& =\left(\left(u_{1}-u_{2}, v\right)\right)-\zeta\left(T\left(u_{1}-u_{2}\right), v\right)+\zeta\left(A u_{1}-A u_{2}, v\right), \text { by }(7) \\
& =\left(\left(u_{1}-u_{2}, v\right)\right)-\zeta\left(\left(\wedge T\left(u_{1}-u_{2}\right), v\right)\right)+\zeta\left(\left(\wedge A u_{1}-\wedge A u_{2}, v\right), \text { by }(8)\right.  \tag{8}\\
& =\left(\left(u_{1}-u_{2},-\zeta T\left(u_{1}-u_{2}\right), v\right)\right)+\zeta\left(\left(A u_{1}-A u_{2}, v\right)\right)
\end{align*}
$$

Thus

$$
\left|\phi\left(\left(\mathrm{u}_{1}\right)-\phi\left(\mathrm{u}_{2}\right), \mathrm{v}\right)\right| \leq\left\|\mathrm{u}_{1}-\mathrm{u}_{2}-\zeta \mathrm{AT}\left(\mathrm{u}_{1}-\mathrm{u}_{2}\right)\right\|\|\mathrm{v}\|+\zeta\left\|\mathrm{Au}_{1}-\mathrm{Au}_{2}\right\|\|\mid \mathrm{v}\|
$$

Now using (7) and (8) we have

$$
\begin{array}{r}
\left\|U_{1}-U_{2}-\zeta \wedge T\left(u_{1}-u_{2}\right)\right\|^{2} \leq\left\|u_{1}-u_{2}\right\|^{2}+\zeta^{2}\|T\|^{2}\left\|u_{1}-u_{2}\right\|^{2}-2 \zeta a\left(u_{1}-u_{2}, u_{1}-u_{2}\right) \\
\leq\left(1+\zeta^{2} \beta^{2}-2 \zeta \alpha\right)\left\|u_{1}-u_{2}\right\|^{2}, \text { by coercivity of } a(u, v)
\end{array}
$$

Then
$\left|\left(\phi\left(u_{1}\right)-\phi\left(u_{2}\right), v\right)\right| \leq \sqrt{\left(1+\zeta^{2} \beta^{2}-2 \zeta \alpha\right)}\left\|u_{1}-u_{2}\right\|\|v\|+\zeta\left\|A u_{1}-A u_{2}\right\|\|v\|$ for all $v \in H$. $\leq \theta\left\|\mathrm{u}_{1}-\mathrm{u}_{2}\right\|\|\mathrm{v}\|$, by the Lipschitz coutinuity of $A$,
and $\theta=\sqrt{1+\zeta^{2} \beta^{2}-2 \zeta \alpha}+\gamma \zeta<1$ for $0<\zeta<2 \frac{\alpha-\gamma}{\beta^{2}-\gamma^{2}}$ and $\zeta<\frac{1}{\gamma}$, becausea $>\gamma$.
Hence for all $\mathrm{u}_{1}, \mathrm{u}_{2} \in \mathrm{H}$

$$
\left\|\phi\left(u_{1}\right)-\phi\left(u_{2}\right)\right\|=\operatorname{Sup}_{v \in H} \frac{\left|\left(\phi\left(u_{1}\right)-\phi\left(u_{2}\right), v\right)\right|}{\|v\|} \leq \theta\left\|u_{1}-u_{2}\right\|
$$

The following results are proved by Mosco [2].

## Lemma 3

Let $M$ be a convex subset of $H$. Then, given $z H$ we have

$$
\mathrm{x}=\mathrm{P}_{\mathrm{M} \mathrm{Z}}
$$

if and only if

$$
\mathrm{x} \mathrm{M} ; \quad((\mathrm{x}-\mathrm{z}, \mathrm{y}-\mathrm{x})) \geq 0 \quad \text { for all } \mathrm{y} \in \mathrm{M} .
$$

where $\mathrm{P}_{\mathrm{M}}$ is the projection of H in M .

Lemma 4.

$$
\mathrm{P}_{\mathrm{M}} \text { is non-expansive, i.e., }
$$

$$
\left\|\mathrm{P}_{\mathrm{M}} \mathrm{Z}_{1}-\mathrm{P}_{\mathrm{M}} Z_{2}\right\| \leq\left\|\mathrm{Z}_{1}-\mathrm{Z}_{2}\right\| \quad \text { for all } \mathrm{z}_{1}, \mathrm{Z}_{2} \in \mathrm{H}
$$

Using the technique of Lions-Stampacchia [ 1 ], we now prove theorem 1,

## Proof of theorem 1,

(a) Uniqueness

Let $u_{i}, i=1,2$ be solutions in M of

$$
a\left(u_{i}, v-u_{i} .\right) \geq\left(A u_{i}-v-u_{i}\right) \quad \text { for all } v \in M
$$

Setting $\mathrm{v}=\mathrm{u}_{3-\mathrm{i}}, \mathrm{i}=1,2$ in the above inequality, by addition we have

$$
\mathrm{a}\left(\mathbf{u}_{1}-\mathbf{u}_{2}, \mathbf{u}_{1}-\mathbf{u}_{2}\right) \leq\left(\mathrm{Au}_{1}-\mathrm{A} \mathbf{u}_{2}, \mathbf{u}_{1}-\mathbf{u}_{2}\right) .
$$

Since $a(u, v)$ is a coercive bilinear form, there exists a constant $a>0$ such that

$$
\alpha\left\|\mathbf{u}_{1}-\mathbf{u}_{2}\right\|^{2} \leq\left(A u_{1}-A u_{2}, \mathbf{u}_{1}-\mathbf{u}_{2}\right) \leq 0
$$

by the antimonotonicity of A. From which the uniqueness of the solution $u \in M$ follows.
(b) Existence

For a fixed $\zeta$ as in Lemma 2, and $u H$, define $\phi(u) \in H^{\prime}$ by (9). By lemma 3, there exists a unique $w \in M$ such that

$$
((w, v-w)) \geq(\phi(u), v-w) \quad \text { for all } v \in M
$$

and $w$ is given by

$$
\mathrm{w}=\mathrm{P}_{\mathrm{M}} \wedge \phi(\mathrm{u})=\mathrm{Tu}
$$

which defines a map from H into M .

Now for all u., u H,

$$
\begin{aligned}
\left\|\mathrm{TU}_{1}-\mathrm{TU}_{2}\right\| & =\left\|\mathrm{P}_{\mathrm{M}} \wedge \phi\left(\mathrm{u}_{1}\right)-\mathrm{P}_{\mathrm{M}} \wedge \phi\left(\mathrm{u}_{2}\right)\right\| \\
& \leq\left\|\wedge \phi\left(\mathrm{u}_{1}\right)-\wedge \phi\left(\mathrm{u}_{2}\right)\right\|, \text { by lemma } 4 \\
& \leq\left\|\phi\left(\mathrm{v}_{1}\right)-\phi\left(\mathrm{u}_{2}\right)\right\| \\
& \leq \theta\left\|\mathrm{u}_{1}-\mathrm{u}_{2}\right\|, \text { by lemma } 2 .
\end{aligned}
$$

Since $\theta<1$. Tu is a contraction and has a fixed point $u=T u$, which belongs to $M$, a closed convex set and satisfies

$$
((\mathrm{u}, \mathrm{v}-\mathrm{u}))>(\phi(\mathrm{u}), \mathrm{v}-\mathrm{u})=((\mathrm{u}, \mathrm{v}-\mathrm{u}))-\zeta[\mathrm{a}(\mathrm{u}, \mathrm{v}-\mathrm{u})-(\mathrm{Au}, \mathrm{v}-\mathrm{u})]
$$

Thus for $\zeta>0$,

$$
a(u, v-u) \geq(A u, v-u) \quad \text { for all } v \in M
$$

showing that u is a unique solution of problem 1.

## Remarks

1 ; It is obvious that for $\mathrm{Au}=\mathrm{F}^{\prime}(\mathrm{u})$, the existence of a unique solution of a variational inequality (4) follows under the assumptions of theorem. 1 .

2: If $A$ is independent of $u$, that is $A u=A^{\prime}$ (say), then the Lipschitz constant $\gamma$ y is zero, and lemma 2 reduces to a lemma of

Lions-Stampacchia [1] and $\zeta$ is a number such that $0<\zeta<\frac{2 \alpha}{\beta^{2}}$.
Consequently theorem 1 is exactly the same as one proved by Lions-Stampacchia for the linear case. It is obvious that our result not only generalizes their result, but also includes it as a special case.

## Method of Approximation

Suppose that the bilinear form is non-negative, i.e.

$$
\begin{equation*}
a(v, v) \geq 0 \quad \text { for all } v \in H \tag{10}
\end{equation*}
$$

Assume that there exists at least one solution $u \in M$ of

$$
\begin{equation*}
a(u, v-u) \geq(A u, v-u) \quad \text { for all } v \in M \tag{11}
\end{equation*}
$$

and $X$ is the set of all solutions of (11). Let, finally, $b(u, v)$ be a coercive bilinear form on $H$, that is there exists a constant $\alpha>0$ such that

$$
\begin{equation*}
b(v, v) \geq \alpha\|v\| \quad \text { for all } v \in H \tag{12}
\end{equation*}
$$

First of all we prove some elementary but important lemmas.

## Lemma 5

If $a(u, v)$ is a non-negative bilinear form and $u \in M$, then the inequality (5) is equivalent to the inequality

$$
\begin{equation*}
a(v, v-u) \geq(A(u), v-u) \quad \text { for all } v \in M \tag{13}
\end{equation*}
$$

## Proof

Let (5) hold, then

$$
a(v, v-u) \geq(A(u), v-u)+a(v-u, v-u) \geq(A(u), v-u), \text { by }(10)
$$

Thus (13) holds;
Conversely let (13) hold, then for all $t \in[0,1]$ and $w \in M, v_{t}=u+t(w-u) \in M$. Setting $v=v_{t}$ in (13) it follows that

$$
a(u, w-u)+t a(w-u, w-u) \geq(A(u), w-u), \text { for all } w \in M .
$$

Letting $\mathrm{t} \rightarrow 0$, (5) follows.
As a consequence of lemma 1 and lemma 5 we have the following result.

## Lemma 6.

If $\mathrm{a}(\mathrm{u}, \mathrm{v})$ is non-negative bilinear form and A is hemicontinuous
antimonotone operator, then the inequality (5) is equivalent to $a(v, v-u) \geq(A(v), v-u) \quad$ for all $v \in M$.

## Theorem 2

If $b(u, v)$ is a coercive continuous bilinear form and $B$ is a Lipschitz continuous antimonotone operator with $Y<\alpha$ then there exists a unique solution $u_{o} \in X$ such that

$$
\begin{equation*}
b\left(u_{o}, v-u_{o}\right) \geq\left(B u_{o}, v-u_{o}\right) \text { for all } v \in x . \tag{14}
\end{equation*}
$$

## Proof:

Obviously $X$ is closed. In order to prove theorem (2), it is enough to show that $X$ is convex. Since $a(u, v)$ is
non-negative, so (11) is equivalent to

$$
a(v, v-u) \geq(A v, v-u), \text { by lemma } 6
$$

Now for all $t \in[0,1], u_{1}, u_{2} \in X$,

$$
\begin{aligned}
a\left(v, v-u_{2}-t\left(u_{1}-u_{2}\right)\right)=a & \left(v, v-u_{2}\right)-t a\left(v, u_{1}-u_{2}\right) \\
& =a\left(v, v-u_{2}\right)-t a\left(v, u_{1}-v+v-u_{2}\right) \\
& =a\left(v, v-u_{2}\right)+t a\left(v, v-u_{1}\right)-t a\left(v, v-u_{2}\right) \\
& =(1-t) a\left(v, v-u_{2}\right)+t a\left(v, v-u_{1}\right) \\
& \geq(1-t)\left(A v, v-u_{2}\right)+t\left(A v, v-u_{1}\right),
\end{aligned}
$$

by lemma 6 .
Thus for all $t \in[0,1], \mathrm{U}_{1}, \mathrm{U}_{2} \in \mathrm{x}, \mathrm{tu}_{1}+(1-\mathrm{t}) \mathrm{u}_{2} \in \mathrm{x}$, which implies that $X$ is a convex set. Hence by theorem (1), there does exist a unique solution $u_{o} \in X$ satisfying (14).

## Theorem 3

Assume that (10) and (12) hold. If $a(u, v)+\in b(u, v)$ is a
continuous bilinear form and $\mathrm{A}, \mathrm{B}$ are both antimonotone Lipschitz continuous with $\mathrm{Y}<\alpha$, then there exists a unique
solution $\mathbf{u}_{\varepsilon} \in \mathrm{M}$ such that

$$
\begin{equation*}
\mathrm{a}\left(\mathrm{u}_{\varepsilon}, \mathrm{v}-\mathrm{u}_{\varepsilon}\right)+\varepsilon \mathrm{b}\left(\mathrm{u}_{\varepsilon}, \mathrm{v}-\mathrm{u}_{\varepsilon}\right) \geq\left(\mathrm{Au}_{\varepsilon}-\varepsilon \mathrm{Bu}_{\varepsilon}, \mathrm{v}-\mathrm{u}_{\varepsilon}\right) \quad \text { for all } \mathrm{v} \in \mathrm{M} . \tag{15}
\end{equation*}
$$

Proof:
Since for $\in>0$ and by (10), (12), the continuous bilinear form $\mathrm{a}(\mathrm{u}, \mathrm{v})+\varepsilon \mathrm{b}(\mathrm{u}, \mathrm{v})$ is coercive on H , then by theorem 1 , there exists a unique $u_{\varepsilon} \in M$ satisfying (15).

Using lemma 1 and the methods of Sibony [4] and
Lions-Stampacchia [ 1 ], we prove that the elements of X can be approximated.

## Theorem 4

Suppose A,B:M $\rightarrow \mathrm{H}^{\prime}$ are both hemicontinuous operators and the assumptions of theorems (2) and (3) hold. If $u_{o}$ is the element of $X$ defined by (14) satisfying

$$
\begin{equation*}
a\left(u_{o}, v-u_{o}\right) \geq\left(A u_{o}, v-u_{o}\right) \quad \text { for all } v \in X \tag{16}
\end{equation*}
$$

and $u_{\varepsilon}$ is the element of $M$ defined by (15), then

$$
\mathrm{u}_{\varepsilon} \rightarrow \mathrm{u}_{\mathrm{o}} \text { strongly in } \mathrm{H} \text { as } \varepsilon \rightarrow 0
$$

## Proof:

Ihis is proved in three steps.

$$
\begin{equation*}
\mathrm{u}_{£} \text { is bounded in } \mathrm{H} \text {. } \tag{i}
\end{equation*}
$$

Setting $v=u_{o}$ in (15) and $v=u_{\varepsilon}$ in (16), we get

$$
\mathrm{a}\left(\mathbf{u}_{\varepsilon}, \mathbf{u}_{\mathrm{o}}-\mathbf{u}_{\varepsilon}\right)+\varepsilon \mathrm{b}\left(\mathbf{u}_{\varepsilon}, \mathbf{u}_{\mathrm{o}}-\mathbf{u}_{\varepsilon}\right) \geq\left(\mathrm{Au}_{\varepsilon}+\varepsilon B \mathbf{u}_{\varepsilon}, \mathbf{u}_{\mathrm{o}}-\mathbf{u}_{\varepsilon}\right)
$$

and

$$
\mathrm{a}\left(\mathrm{u}_{\mathrm{o}}, \mathrm{u}-\mathrm{u}_{\mathrm{o}}\right) \geq\left(\mathrm{Au} \mathrm{u}_{\mathrm{o}}, \mathrm{u}_{\varepsilon}-\mathrm{u}_{\mathrm{o}}\right)
$$

By addition of these inequalities, it follows from (10) and the antimonotonicity of A that

$$
\begin{equation*}
\mathrm{b}\left(\mathrm{u}_{\varepsilon}, \mathrm{u}_{\mathrm{o}}-\mathrm{u}_{\varepsilon}\right) \geq\left(\mathrm{Bu}_{\varepsilon}, \mathrm{u}_{\mathrm{o}}-\mathrm{u}_{\varepsilon}\right) \tag{17}
\end{equation*}
$$

Since $\mathrm{b}\left(\mathrm{u}_{\varepsilon}, \mathrm{u}_{\varepsilon}\right)$ is a coercive bilinear form, there exists a constant a $>0$ such that

$$
\alpha\left\|\mathbf{u}_{\varepsilon}\right\|^{2} \leq \mathrm{b}\left(\mathbf{u}_{\varepsilon}, \mathbf{u}_{\mathrm{o}}\right)+\left(\mathrm{Bu}_{\varepsilon}, \mathbf{u}_{\varepsilon}-\mathbf{u}_{\mathrm{o}}\right) .
$$

It follows that $\left\|\mathrm{u}_{\varepsilon}\right\| \leq$ constant, independent of $\varepsilon$.
Hence there exists a subsequence $u_{\varepsilon}$ which converges to $\xi$, say.
(ii)

$$
\xi \text { belongs to } \mathrm{X} .
$$

Since A and B are antimonotone operators, by (15)
and the application of lemma 1 , we get

$$
\mathrm{a}\left(\mathrm{u}_{\varepsilon}, \mathrm{v}-\mathrm{u}_{\varepsilon}\right)+\varepsilon \mathrm{b}\left(\mathrm{u}_{\varepsilon}, \mathrm{v}-\mathrm{u}_{\varepsilon}\right) \geq(\mathrm{Av}+\varepsilon \mathrm{Bv}, \mathrm{v}-\mathrm{u} \varepsilon) \quad \text { for all } \mathrm{v} \in \mathrm{M} .
$$

Now let $\varepsilon \rightarrow 0$, then $\mathbf{u}_{\varepsilon} \rightarrow \xi$ and $\lim \inf \mathbf{a}\left(\mathbf{u}_{\varepsilon}, \mathbf{u}_{\varepsilon}\right) \geq \mathrm{a}(\xi, \xi),[1]$ We have

$$
a(\xi, v-\xi) \geq(A v, v-\xi) \quad \text { for all } v \in X
$$

which is by lemma 1 equivalent to

$$
a(\xi, v-\xi) \geq(A \xi, v-\xi) \quad \text { for all } v \in X
$$

Thus $\xi \in X$.
(iii) $\quad$ Finally $\left\|\mathbf{u}_{\varepsilon}\right\| \rightarrow\|\mathrm{c}\|$ when $\varepsilon \rightarrow 0$,

$$
\text { Setting } v=u \in X \text { in (15) and } v-u_{\varepsilon} \in X \text { in (11) }
$$

We obtain

$$
\mathrm{a}\left(\mathbf{u}_{\varepsilon}, \mathrm{u}-\mathbf{u}_{\varepsilon}\right)+\varepsilon \mathrm{b}\left(\mathbf{u}_{\varepsilon}, \mathrm{u}-\mathbf{u}_{\varepsilon}\right) \geq\left(\mathrm{A} \mathbf{u}_{\varepsilon}+\varepsilon B \mathbf{u}_{\varepsilon}, \mathbf{u}-\mathbf{u}_{\varepsilon}\right),
$$

which is, by lemma 1 , equivalent to

$$
\mathrm{a}\left(\mathbf{u}_{\varepsilon}, \mathbf{u}-\mathbf{u}_{\varepsilon}\right)+\varepsilon \mathrm{b}\left(\mathbf{u}_{\varepsilon}, \mathbf{u}-\mathbf{u}_{\varepsilon}\right) \geq\left(\mathrm{Au}+\varepsilon \mathrm{Bu}, \mathbf{u}-\mathbf{u}_{\varepsilon}\right)
$$

Also,

$$
\mathrm{a}\left(\mathrm{u}, \mathrm{u}_{\varepsilon}-\mathrm{u}\right) \geq\left(\mathrm{Au}, \mathrm{u}_{\varepsilon}-\mathrm{u}\right)
$$

By addition one has

$$
\mathrm{a}\left(\mathrm{u}_{\varepsilon}-\mathrm{u}, \mathrm{u}-\mathrm{u}_{\varepsilon}\right)+\varepsilon \mathrm{b}\left(\mathrm{u}_{\varepsilon}, \mathrm{u}-\mathrm{u}_{\varepsilon}\right) \geq \varepsilon\left(\mathrm{Bu}, \mathrm{u}-\mathrm{u}_{\varepsilon}\right)
$$

Using (10), and for $\varepsilon>0$, we get

$$
\mathrm{b}\left(\mathrm{u}_{\varepsilon}, \mathrm{u}-\mathrm{u}_{\varepsilon}\right) \geq\left(\mathrm{Bu}, \mathrm{u}-\mathrm{u}_{\varepsilon}\right) \quad \text { for all } \mathrm{u} \in \mathrm{X}
$$

Letting $\varepsilon \rightarrow 0, u_{\varepsilon} \rightarrow \xi$, we have

$$
\mathrm{b}(\xi, \mathrm{u}-\xi) \geq(\mathrm{Bu} \cdot \mathrm{u}-\xi)
$$

$$
\geq(\mathrm{B} \xi, \mathrm{u}-\xi), \quad \text { by lemma } 1
$$

Thus $\xi \in X$ is a solution of (14) and since the solution is unique, it follows that $\xi-u_{o}$.

Also from (17), by the coercivity of $b\left(u_{\varepsilon}, u_{\varepsilon}\right)$, it follows that there exists a constant $\alpha>0$ such that

$$
\begin{aligned}
& \alpha\left\|u_{\varepsilon}-u_{o}\right\| \leq b\left(u_{\varepsilon}-u_{o}, u_{\varepsilon}-u_{o}\right) \\
& \leq\left(B u_{\varepsilon}, u_{\varepsilon}-u_{o}\right)-b\left(u_{o}, u_{\varepsilon}-u_{o}\right) \\
& \leq\left(B u_{o}, u_{\varepsilon}-u_{o}\right)-b\left(u_{o}, u_{\varepsilon}-u_{o}\right) \text {, by lennna } 1 \text {, }
\end{aligned}
$$

which $\rightarrow 0$, as, $\varepsilon \rightarrow 0$. Hence it follows that $\mathrm{u}_{\varepsilon} \rightarrow$ u strongly in $H$.

## Theorem 5

If $a(u, v), b(u, v)$ are coercive continuous bilinear forms, $M$ is a closed convex set in $H$, and $A, B$ are heniicontinuous antimonotone Lipschitz continuous operators with $\alpha>\gamma$, then problem 1 has a
unique solution if and only if there exists a constant $L$, independent of $\varepsilon$, such that the solution of (15) satisfies

$$
\begin{equation*}
\left\|\mathbf{u}_{\varepsilon}\right\| \leq \mathrm{L} \tag{18}
\end{equation*}
$$

Proof:
If there exists a solution, then from theorem 4, it follows that (18) holds. Conversely suppose that (18) holds, then there exists a subsequence $u_{\eta}$ of $u_{\varepsilon}$ which converges to
$w$ weakly in $H$. Since $M$ is a closed convex set, $w \in M$, Further writing (15) in. the form

$$
\mathrm{a}(\mathrm{u}, \mathrm{u}-\mathrm{v})+\varepsilon \mathrm{b}\left(\mathrm{u}_{\varepsilon}, \mathrm{u}_{\varepsilon}-\mathrm{v}\right) \leq\left(\mathrm{Av}+\varepsilon \mathrm{Bv}, \mathrm{u}_{\varepsilon}-\mathrm{v}\right) \quad \text { for all } \mathrm{v} \in \mathrm{M}
$$

and taking $\varepsilon=\eta=0$, we find that

$$
a(w, w) \leq a(w, v)+(A v, w-v) \quad \text { for all } v \in M,
$$

which is by lemma 1 , equivalent to

$$
a(w, w-v) \leq(A w, w-v) \quad \text { for all } v \in M
$$

Thus $w$ is the solution satisfying (11).

## Existence of Solutions

In this section, the existence of the solution satisfying (10) for the cases, when $M$ is bounded or an unbounded convex subset of H is considered.

## Theorem 6

If $M$ s a bounded closed convex subset, and $A$ is a hemicontinuous Lipschiltz antimono tone operation, then there exists a unique solution of problem (1).

## Proof:

Let $u_{\varepsilon} \in M$ be the element defined by (15). Since $M$ is bounded, then $\left\|\mathrm{u}_{\varepsilon}\right\|$ is bounded, and theorem (6) follows from theorem (5).

Consider now the case when the set M is bounded. Let $\mathrm{M}_{\mathrm{R}}=\{\mathrm{k} ; \mathrm{k} \in \mathrm{M},| | \mathrm{k} \| \leq \mathrm{R}\}$ with R large enough so that $\mathrm{M}_{\mathrm{R}} \neq \phi$. Assume that A is hemicontinuous antimonotone operator, then by theorem (6), there exists a non-empty set,
$X_{R} \equiv$ set of all solution of $w \in M_{R}$ with
$a(w, v-w) \geq(A w, v-w) \quad$ for all $v \in M_{R}$

## Theorem 7

Suppose $a(u, v)$ is a continuous bilinear form and $A$ is a hemicontinuous antimonotone operator. If $u \in X_{R}$ with $\|u\|<R$, then $u$ satisfies (11).

Proof
In fact, let $w$ be any solution in $M$. Then for
$0<\varepsilon<1, \mathbf{u}+\varepsilon(\mathbf{w}-\mathbf{u}) \in \mathrm{M}$ and $\|\mathbf{u}+\in(\mathrm{w}-\mathbf{u})\| \leq\|\mathbf{u} \mid+\varepsilon\| \mathrm{w}-\mathrm{u} \|<\mathrm{R}$ for sufficiently small $\varepsilon$. Thus for $0<\varepsilon<\varepsilon_{1}, \mathrm{v}=\mathrm{u}+\varepsilon(\mathrm{w}-\mathrm{u}) \in \mathrm{M}_{\mathrm{R}}$.

Consequently such a v is allowed in (19) with $\mathrm{w}=\mathrm{u}$ and it follows that

$$
a(u, w-u) \geq(A u, w-u) \quad \text { for all. } w \in M .
$$

This proves theorem 7.

Let $\mathrm{a}(\mathrm{u}, \mathrm{v})$ be a coercive continuous bilinear form on H . The Cauchy-Schwarz inequality holds for $a(u, v)$ and is given by

$$
|a(u, v)|^{2} \leq a(u, u) a(v, v) \quad \text { for all } u, v \in H
$$

## Theorem 8

A bounded bilinear form is continuous with respect to the norm convergence.

Proof:

Let $u_{n} \rightarrow u$ and $v_{n} \rightarrow v$, these sequences are bounded. We let Y be their bound, and then $\left\|\mathrm{u}_{\mathrm{n}}\right\| \leq \mathrm{Y}$.

Now

$$
\begin{aligned}
{\left[a\left(u_{n}, v_{n}\right)-a(u, v) \mid\right.} & =\left|a\left(u_{n}, v_{n}\right)-a\left(u_{n}, v\right)+a\left(u_{n}, v\right)-a(u, v)\right| \\
& \leq\left|a\left(u_{n}, v_{n}-v\right)\right|+\left|a\left(u_{n}-u, v\right)\right| \\
& \leq C \gamma\left\|v_{n}-v\right\|+C_{1}\left\|u_{n}-u\right\|\|v\|
\end{aligned}
$$

by the Cauchy-Schwarz inequality. But $\left\|\mathbf{u}_{\mathrm{n}}-\mathbf{u}\right\| \rightarrow 0$ and
$\|\left[\mathrm{v}_{\mathrm{n}}-\mathrm{v} \| \rightarrow 0\right.$ as $\mathrm{n} \rightarrow{ }^{\infty}$, and therefore
$\left|\mathrm{a}\left(\mathrm{u}_{\mathrm{n}}, \mathrm{v}_{\mathrm{n}}\right)-\mathrm{a}(\mathrm{u}, \mathrm{v})\right| \rightarrow 0$, i.e.,
$a\left(u_{n}, v_{n}\right) \rightarrow a(u, v)$.

## Theorem 9

Let $v$ be in $H$ and $M$ be a closed convex subset of $H$. If $u$ is a minimizing vector and $\mathrm{a}(\mathrm{x}, \mathrm{v})$ is any continuous bilinear form such
that $\mathrm{a}(\mathrm{x}, \mathrm{y})=((\mathrm{x}, \mathrm{y}))$, for all $\mathrm{x}, \mathrm{y} \in \mathrm{H}$, then

$$
\begin{equation*}
a(u-v, w-u) \geq 0 \quad \text { for all } w \in M \tag{20}
\end{equation*}
$$

Conversely if (19) holds and $a(u, v)$ Is also coercive, then

$$
\|u-v\| \leq \alpha^{-1} c\|w-v\| \text { for all } w \in M
$$

## Proof:

If $u$ is the unique minimizing vector, then we have to show that $a(u-v, w-u) \geq 0$ for all $w \in M$.

Suppose to the contrary that there is a vector $\mathrm{v}_{1} \in \mathrm{M}$ such that $a\left(u-v, u-v_{1}\right)=\varepsilon>0$. For all $t \in[0,1]$ and $v_{1} \in M$, $\mathrm{v}_{\mathrm{t}} \equiv \mathrm{u}+\mathrm{t}\left(\mathrm{v}_{\mathbf{1}}-\mathrm{u}\right) \in \mathrm{M}$,

Now

$$
\begin{aligned}
\left\|\mathrm{v}_{\mathrm{t}}-\mathrm{v}\right\|^{2} & =\left\|\mathrm{u}+\mathrm{t}\left(\mathrm{v}_{1}-\mathrm{u}\right)-\mathrm{v}\right\|^{2} \\
& =\|\mathbf{u}-\mathrm{v}\|^{2}+\mathrm{t}^{2}\left\|\mathrm{v}_{1}-\mathrm{u}\right\|^{2}+2 \mathrm{t}\left(\mathrm{u}-\mathrm{v}, \mathrm{v}_{1}-\mathrm{u}\right) \\
& <\|\mathrm{u}-\mathrm{v}\|^{2}
\end{aligned}
$$

for, small positive $t$, which contradicts the minimizing property of $u$. Hence no such $v_{1}$ can exist.

Conversely let ueM such that (20) holds, then for any $\mathbf{w} \neq \mathbf{u}, \mathbf{w} \in \mathrm{M}$,

$$
0 \leq a(u-v, w-u)=a(u-v, w-v+v-u)
$$

implies that

$$
a(u-v, u-v) \leq a(u-v, w-v) .
$$

Since $a(u, v)$ is a continuous coercive bilinear form, there exist constants $\mathrm{c}>0, \alpha>0$ such that

$$
\alpha\|u-v\|^{2} \leq c\|u-v\|\|w-v\| \quad \text { for all } w \in M
$$

i.e.,

$$
\|u-v\| \geq a^{-1} c\|w-v\| \quad \text { for all } w \in M
$$

The following representation of the differentiable
functions is needed

$$
F(u)-F(v)={ }_{o} \int^{1}\left(u-v, F^{\prime}(v+s(u-v)) d s\right.
$$

## Theorem 10.

If $F^{\prime}$ is antimonotone, then the real-valued functional $F$ is weakly upper semicontinuous and concave.

## Proof:

Consider

$$
\begin{aligned}
F\left(u_{n}\right)-F(u) & ={ }_{o} \int^{1}\left(u_{n}-u, F^{\prime}\left(u+s\left(u_{n}-u\right)\right) d s\right. \\
& ={ }_{o} \int^{1}\left(u_{n}-u, F^{\prime}(u) d s+{ }_{o} \int^{1}\left(u_{n}-u, F^{\prime}\left(u_{n}+s\left(u_{n}-u\right)\right)-F^{\prime}(u)\right) d s\right.
\end{aligned}
$$

If $\mathrm{u}_{\mathrm{n}} \rightarrow \mathrm{u}$ weakly, as $\mathrm{n} \rightarrow \infty$, then the first term on R.H.S.
tends to zero. The second term is always non-positive. In fact, by antimonotonicity $\left(\mathrm{u}_{\mathrm{n}}-\mathrm{u}, \mathrm{F}^{\prime}\left(\mathrm{u}+\mathrm{s}\left(\mathrm{u}_{\mathrm{n}}-\mathrm{u}\right)\right)-\mathrm{F}^{\prime}(\mathrm{u})\right) \leq 0$ for all $0 \leq \mathrm{s} \leq 1$, and therefore the integrand $\leq 0$ for all $0 \leq \mathrm{s} \leq 1$. Hence for a sufficiently large $n$, there exists $\varepsilon_{n} \rightarrow 0$ as $n \rightarrow \infty$ such that $F(u)-F(u) \leq \varepsilon_{n}$, i.e.,

$$
\lim _{\mathrm{n} \rightarrow \infty} \sup \mathrm{~F}\left(\mathrm{u}_{\mathrm{n}}\right) \leq \mathrm{F}(\mathrm{u})
$$

Thus F is a weakly upper semicontinuous functional. Using a similar argument, it can be seen that the antimenotonicity of $\mathrm{F}^{\prime}$ guarantees concavity of F .

## Theorem 11.

If a functional $F$ is concave on a convex set $M$, then the

Frechet differential $\mathrm{F}^{\prime}$ of F is antimonotone .

Proof:
For all $t \in[0,1]$ and $u, v \in M, t u+(1-t) v=v+t(u-v) \in M$.
By definition

$$
\mathrm{F}(\mathrm{v}+\mathrm{t}(\mathrm{u}-\mathrm{v}) \geq \mathrm{t} F(\mathrm{u})+(1-\mathrm{t}) \mathrm{F}(\mathrm{v})
$$

Dividing both sides by $t$, and letting $t \rightarrow 0$, we get

$$
\left.F^{\prime}(v), u-v\right) \geq F(u)-F(v)
$$

Similarly

$$
\left(\mathrm{F}^{\prime}(\mathrm{u}), \mathrm{v}-\mathrm{u}\right) \geq \mathrm{F}(\mathrm{v})-\mathrm{F}(\mathrm{u})
$$

By addition, it follows that

$$
\left(F^{\prime}(v)-F^{\prime}(u), u-v\right) \geq 0 \quad \text { for all } u, v \in M
$$

Thus from theorem 10 and theorem 11 one concludes that "A real-valued functional on a convex set in a Hilbert space is concave if and only if its Frechet differential is an antimonotone operator".

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