



Brunel
University
London

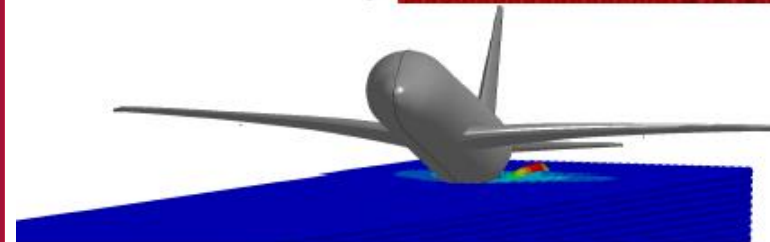
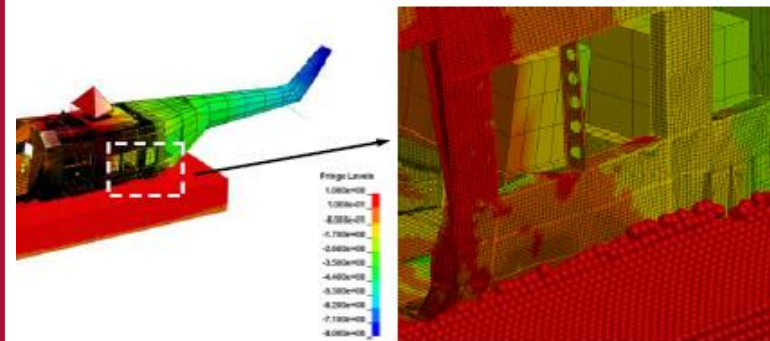
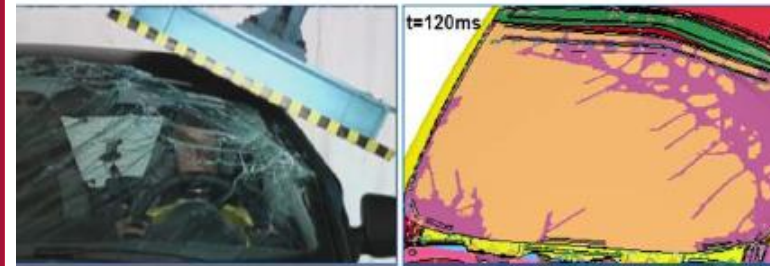
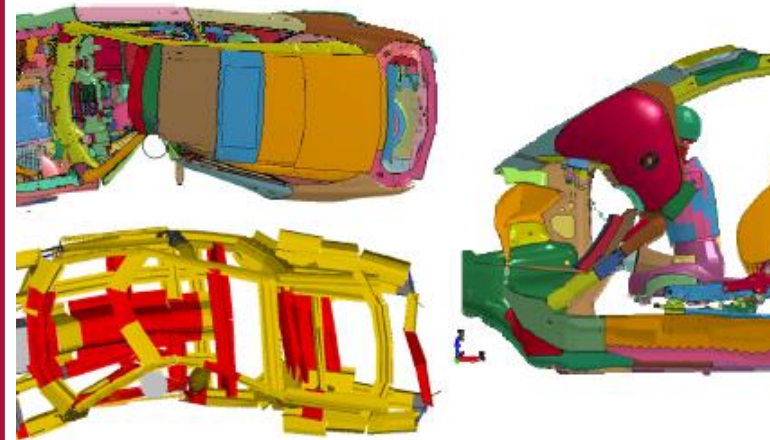
EXTREME

ECCM18, Athens, Greece
24-28 June 2018

Instabilities due to Strain-Softening Solved using the SPH Method

Dr Nenad Djordjevic*
Prof Rade Vignjevic**
Dr Tom De Vuyst
Dr Simone Gemkow

*** nenad.djordjevic@brunel.ac.uk**
**** v.rade@brunel.ac.uk**



Outline

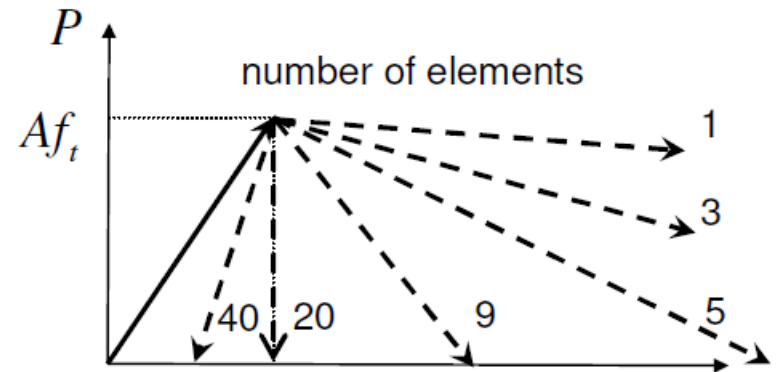
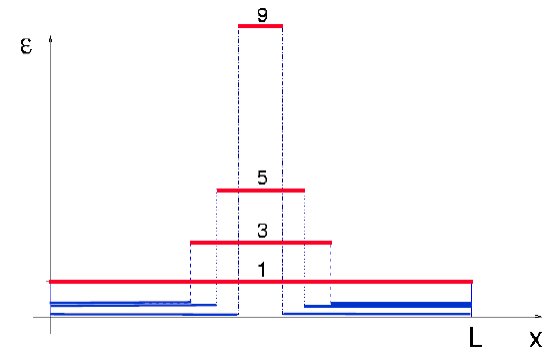
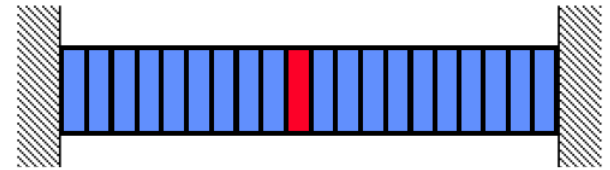
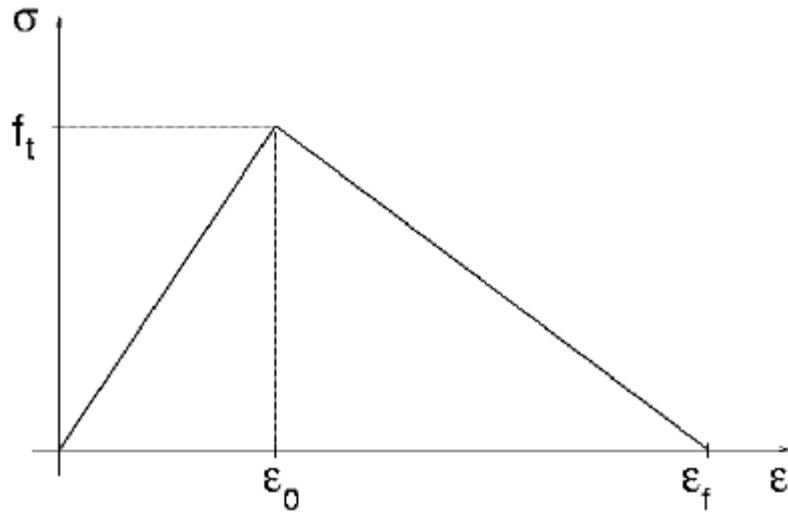
- Introduction
- Strain Softening Problem
- Computational Models for Strain Softening Problem
- Numerical Experiments
 - FEM Results for wave propagation problem
 - SPH Results for wave propagation problem
 - SPH Results for cube impact on a flat plate
- Conclusions and Future Work

Acknowledgement: The project leading to this presentation has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 636549.

Introduction

- EXTREME project aims at development novel material characterisation and in-situ measurement methods, **material models** and **improvement of computational methods** for the design and manufacture aerospace composite structures under EXTREME dynamic loadings leading to a significant reduction of weight, design and certification cost.
- This work is aimed at development of technique to address the **localisation** and **material softening** problem, including a treatment of material softening due to damage, in order to reduce and ultimately remove mesh dependency;
- Strain softening effects have been analysed in FEM and SPH method using CDM approach;

Strain Softening Problem

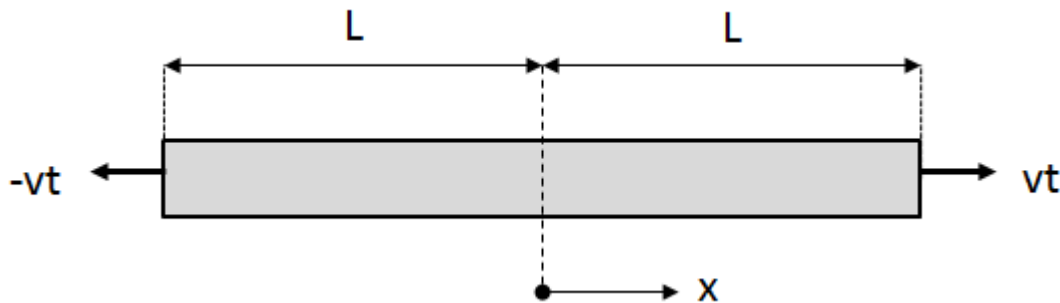


Strain Softening Problem

- Damage in the local continuum damage mechanics (CDM) is modelled as a degeneration of material properties induced by mechanical loading, which can result in strain softening behaviour;
- This can lead to an ill-posed boundary value problem, where the local governing hyperbolic differential equations at a point become elliptic, which induces a numerical instability;
- This instability is mesh-sensitive and manifests itself as non-physical deformation of the softening continuum;
- This work primarily considered the strain-softening effects in the SPH spatial discretisation, and compares those with the classical CDM-FEM solutions;

Strain Softening Problem

- One-dimensional dynamic strain softening problem, for which an exact analytical solution for wave propagation was known (Bažant and Belytschko, 1985)



$$\dot{\epsilon}_{ij} \dot{\sigma}_{ij} > 0$$

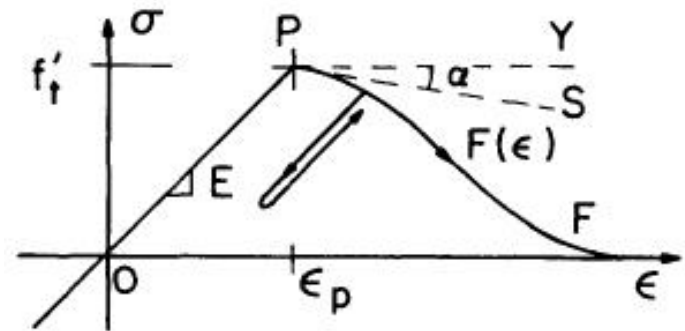
Bifurcation criterion

$$\dot{\sigma}_{ij} = \mathbb{C}_{ijkl} \dot{\epsilon}_{kl}$$

Rate form of constitutive equation

$$c^2 \frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 u}{\partial t^2}$$

Elastic response



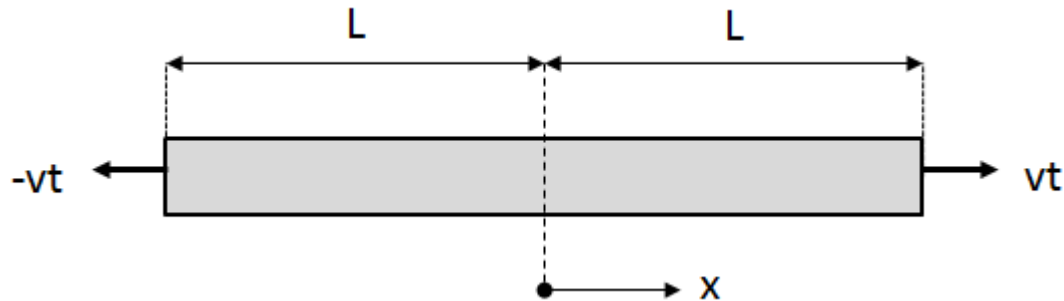
Material stability criterion

$$\dot{\epsilon}_{ij} \mathbb{C}_{ijkl} \dot{\epsilon}_{kl} = 0$$

Softening response

$$c^2 \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial t^2} = 0 \quad c^2 = \frac{F'(\epsilon)}{\rho}$$

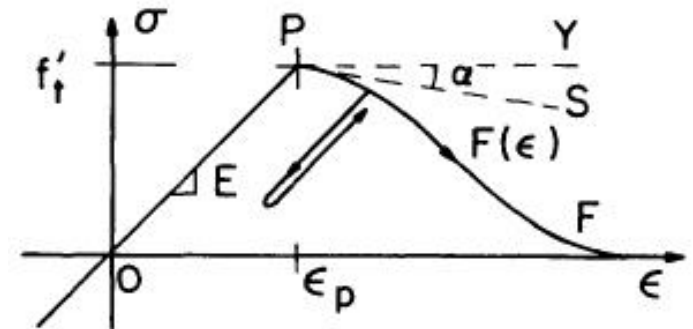
Strain Softening Problem



$$u(x, t) = -v \left\langle t - \frac{x+L}{c} \right\rangle + v \left\langle t + \frac{x-L}{c} \right\rangle$$

$$\varepsilon_x = \frac{\partial u}{\partial x} = \frac{v}{c} \left[H \left(t - \frac{x+L}{c} \right) + H \left(t + \frac{x-L}{c} \right) \right]$$

$$\varepsilon_x = \frac{v}{c} \left[H \left(t - \frac{x+L}{c} \right) - H \left(t + \frac{x-L}{c} \right) + 4v \left\langle t - L/c \right\rangle \delta(x) \right]$$

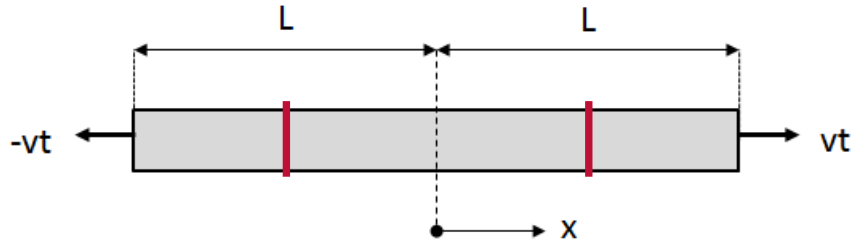


Analytical solution for displacement field

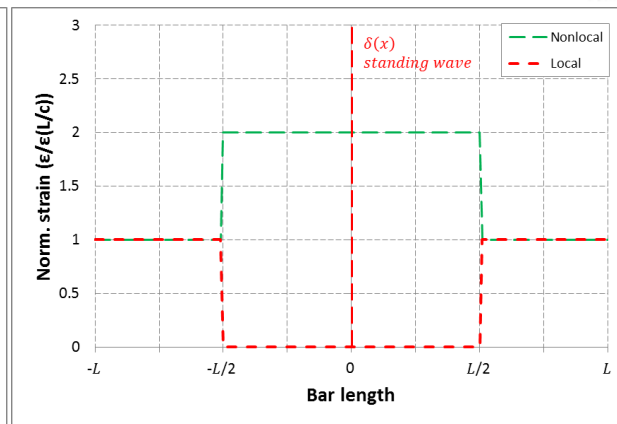
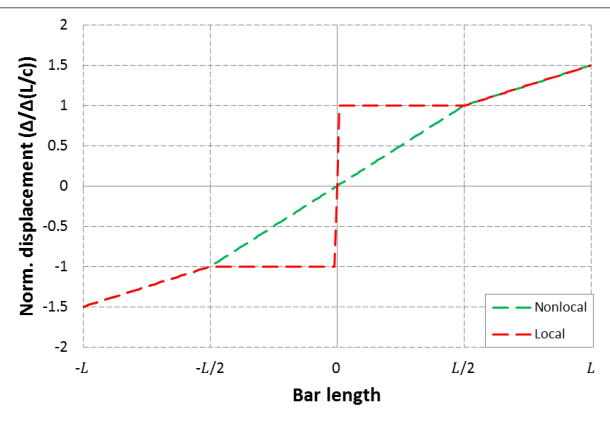
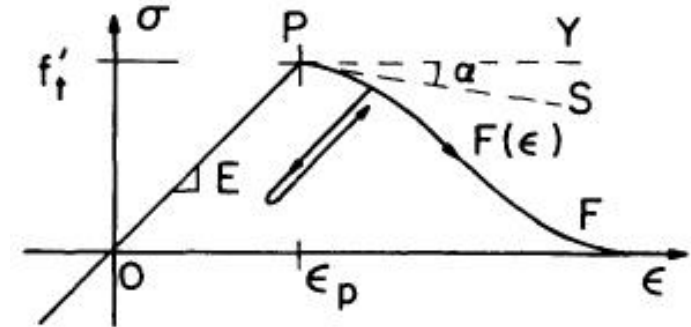
Strain field before the wave superposition in the midsection of the bar

Strain field outside of the softening zone

Strain Softening Problem

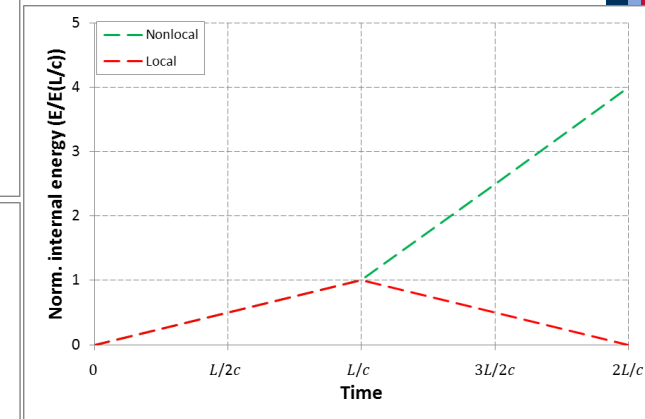
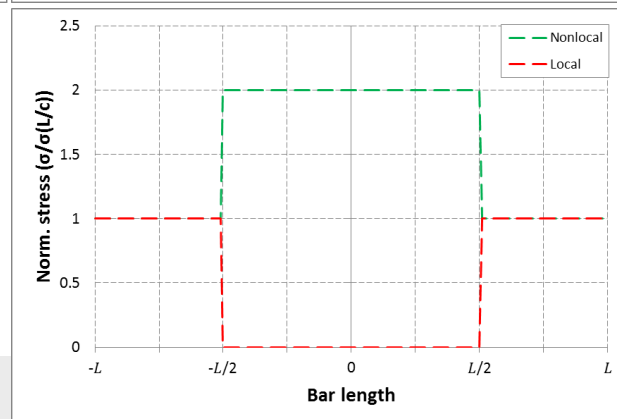


Geometry and loading of softening bar Bažant and Belytschko (1985)



Local and nonlocal solutions at the time instance

$$t = \frac{3L}{2c}$$

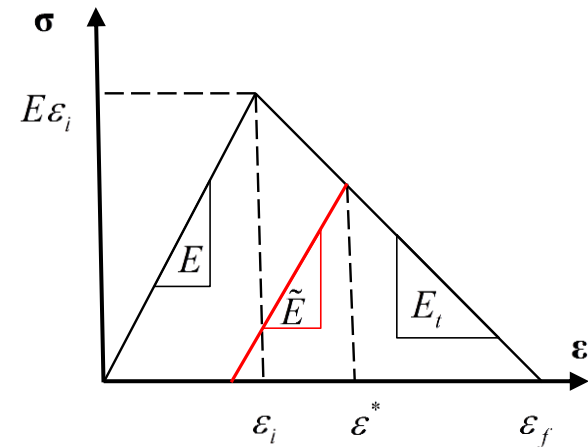


Constitutive Model with Isotropic Damage

- Bilinear constitutive law based on local continuum damage mechanics approach;

$$\bar{\sigma} = \frac{\sigma}{1-\omega} \quad \omega = 1 - \frac{\varepsilon_i (\varepsilon_f - \varepsilon^*)}{\varepsilon^* (\varepsilon_f - \varepsilon_i)}$$

$$E_T = -\frac{E\varepsilon_i}{\varepsilon_f - \varepsilon_i}$$

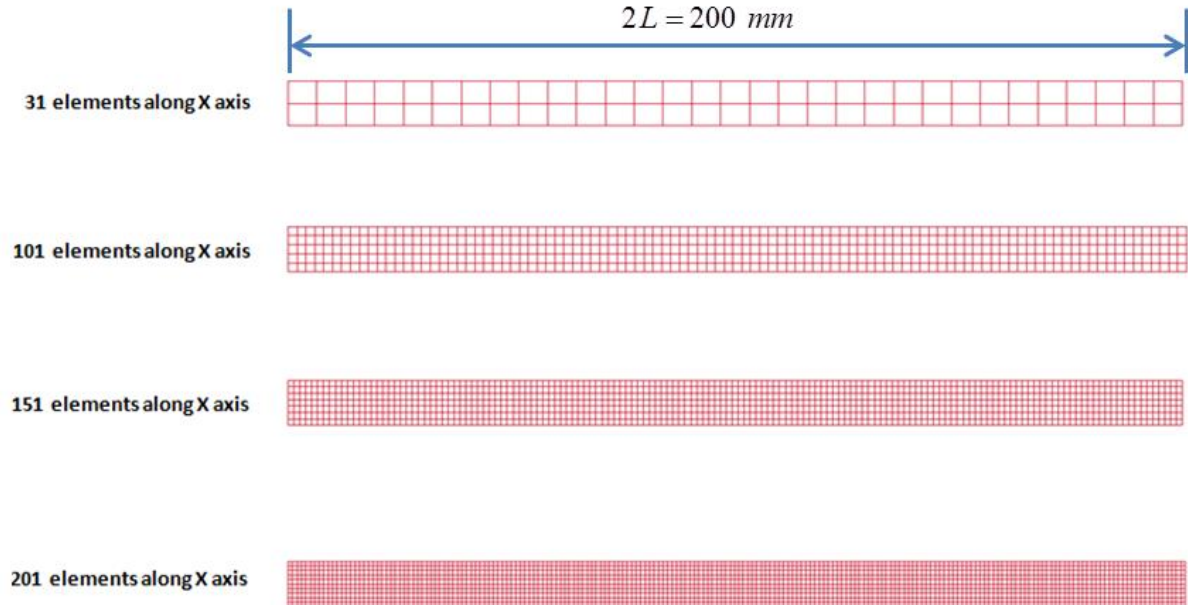


- Two discretisation methods:
 - Finite Elements Method (FEM);
 - Smooth Particle Hydrodynamics (SPH);

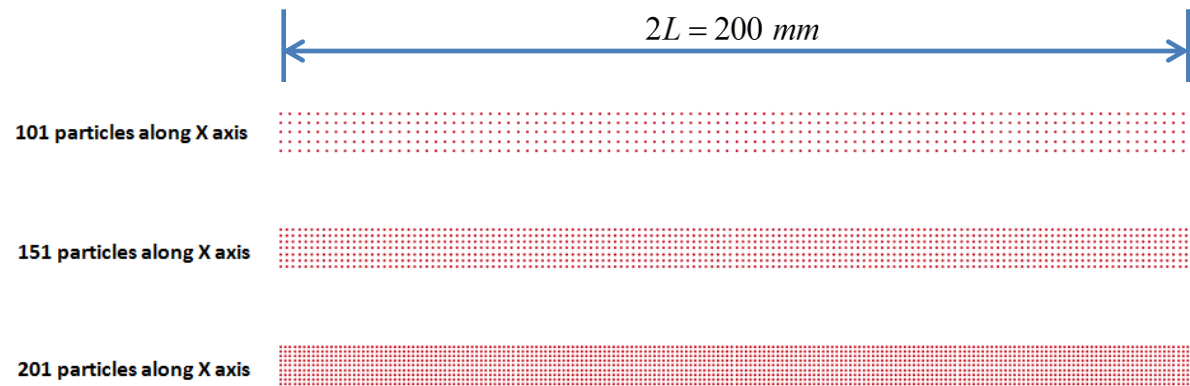
Numerical Experiments

FEM and SPH Models

**Spatial discretisation
used in the FEM
(DYNA3D) simulation
of the strain-
softening bar**



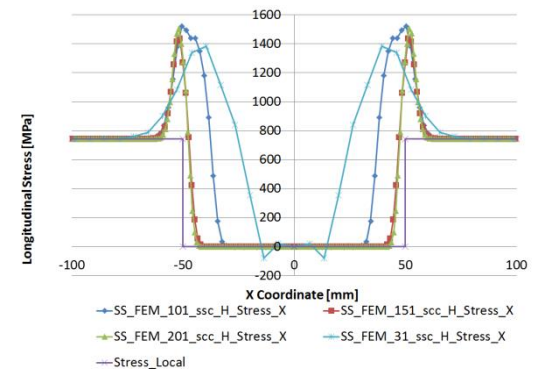
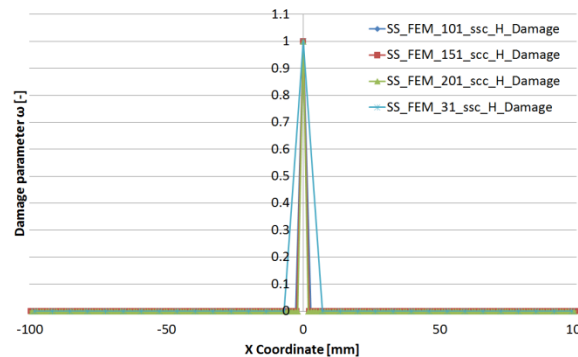
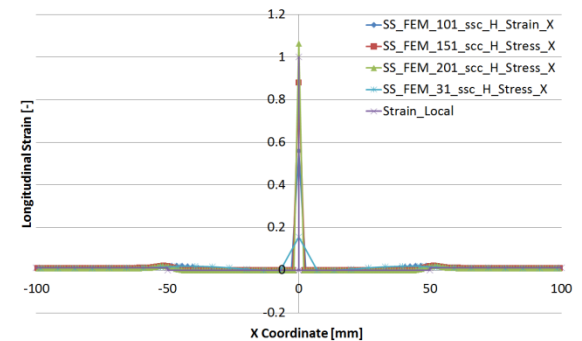
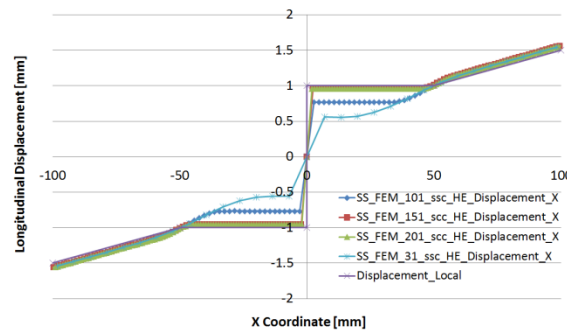
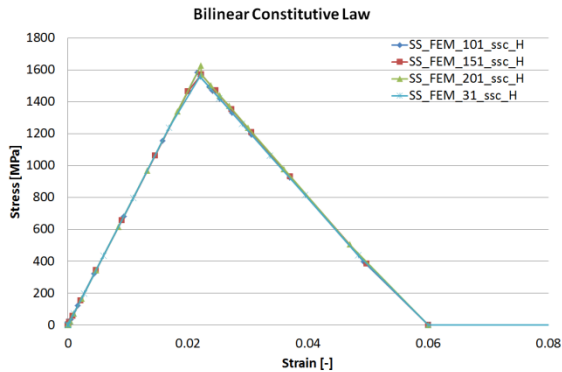
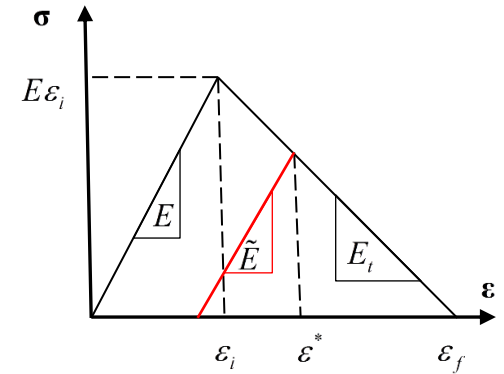
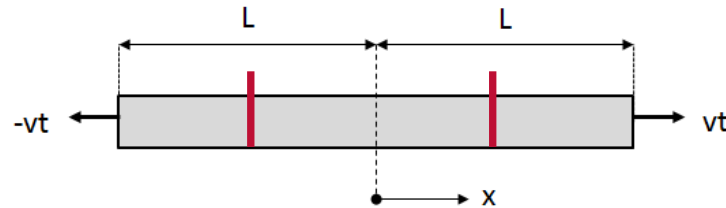
**Particle discretisation
in SPH (MCM) of
strain-softening bar**



Numerical Experiments

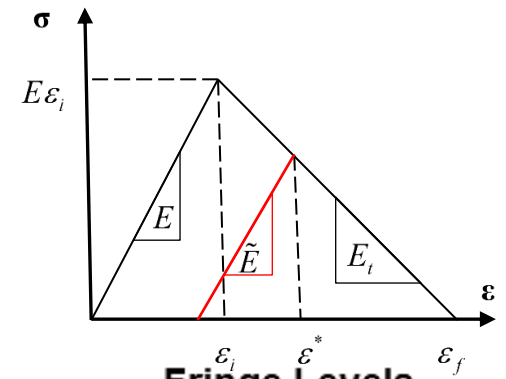
FEM Results

Bilinear law implemented in FEM using a damage parameter and classic CDM approach



Numerical Experiments

FEM Results



Fringe Levels

1.000e+00

9.000e-01

8.000e-01

7.000e-01

6.000e-01

5.000e-01

4.000e-01

3.000e-01

2.000e-01

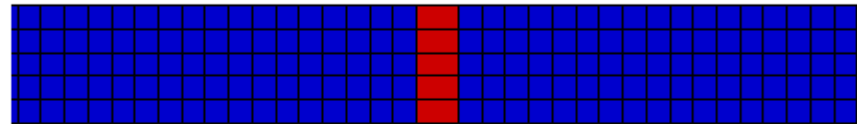
1.000e-01

0.000e+00

31 elements along X axis



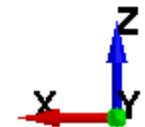
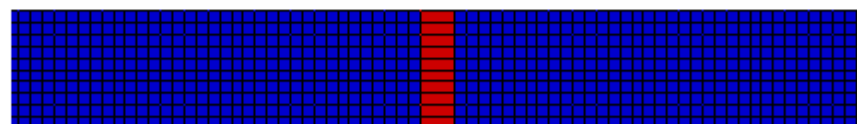
101 elements along X axis



151 elements along X axis

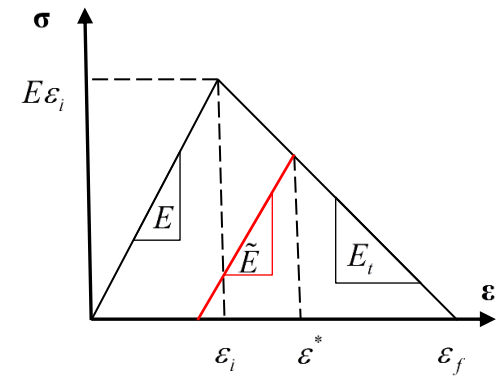


201 elements along X axis



Numerical Experiments

Smooth Particle Hydrodynamics



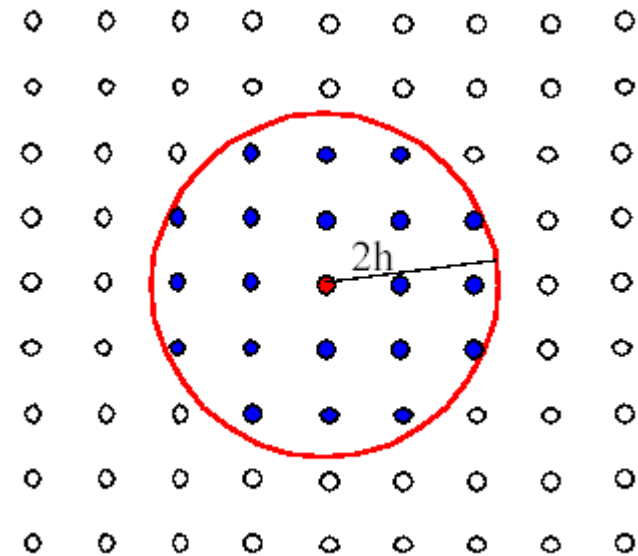
- SPH is a meshless particle method, where the motion of a continuum is described by the movement of a finite number of discrete particles, which are used in the spatial discretisation of the state variables;

$$\langle f(\mathbf{x}) \rangle = \int_{\Omega} f(\mathbf{x}') W(|\mathbf{x} - \mathbf{x}'|, h) d\mathbf{x}'$$

$$\langle f(\mathbf{x}_I) \rangle \approx \sum_J^N \frac{m_J}{\rho_J} f(\mathbf{x}_J) [W(|\mathbf{x}_I - \mathbf{x}_J|, h)]$$

$$\nabla f(\mathbf{x}_I) = \sum_J \frac{m_J}{\rho_J} f(\mathbf{x}_J) [\nabla W(|\mathbf{x}_I - \mathbf{x}_J|, h)]$$

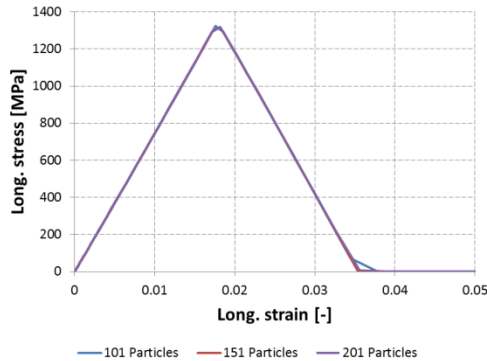
$$\langle \mathbf{F}_i \rangle = - \sum_{j=1}^{np} \frac{m_j}{\rho_j^0} (\mathbf{v}_i - \mathbf{v}_j) \otimes \nabla_{\mathbf{x}_i^0} W(|\mathbf{x}_i^0 - \mathbf{x}_j^0|, h^0)$$



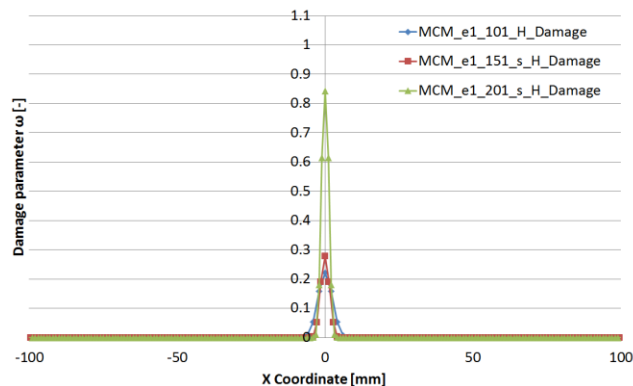
$$h = \lambda \Delta p$$

Numerical Experiments

SPH Results of Experiment 1 – inter-particle distance

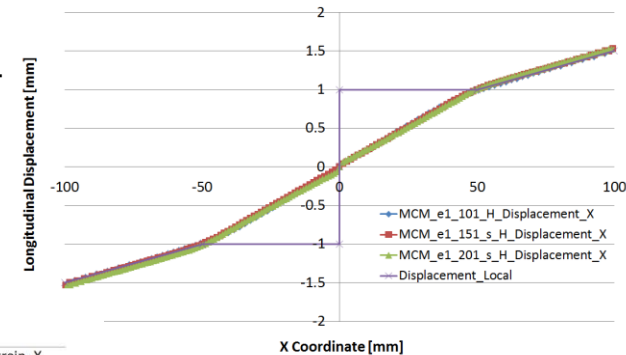


Longitudinal stress vs. longitudinal strain curves for the central particle for different values of Δp , SPH

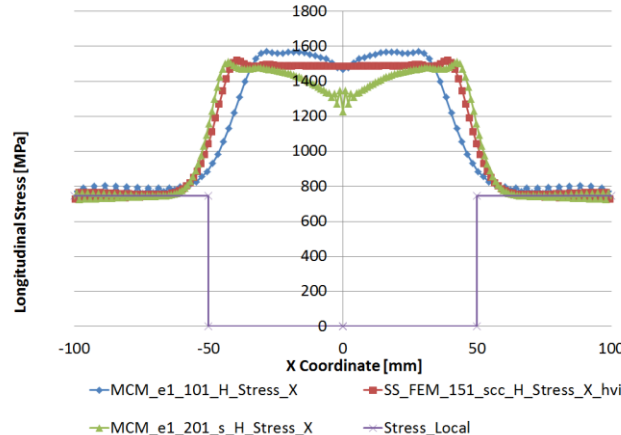
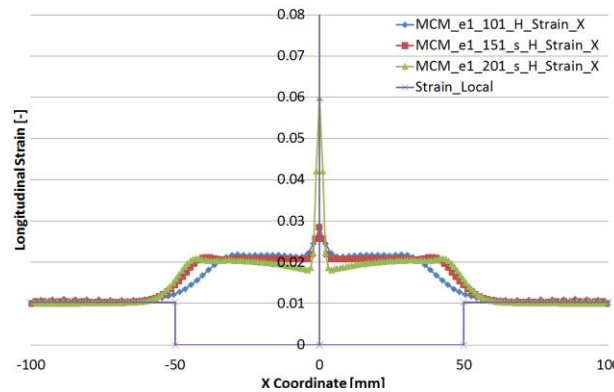


Damage distribution for different particle densities, SPH-experiment 1, response time $t = 3/2 \cdot L/c_e$

Analytical solution and the SPH-experiment 1 numerical results for longitudinal displacement at $t = 3/2 \cdot L/c_e$



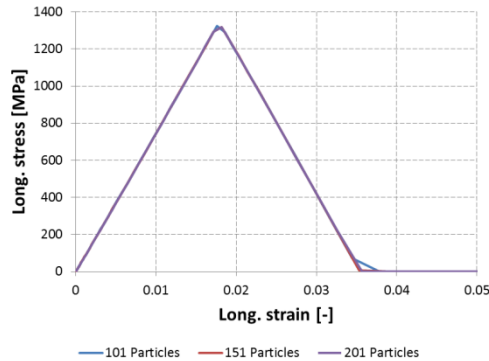
Analytical solution and the SPH-experiment 1 numerical results for longitudinal strain at $t = 3/2 \cdot L/c_e$



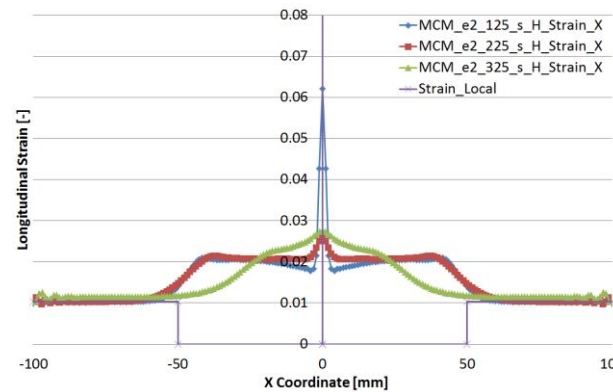
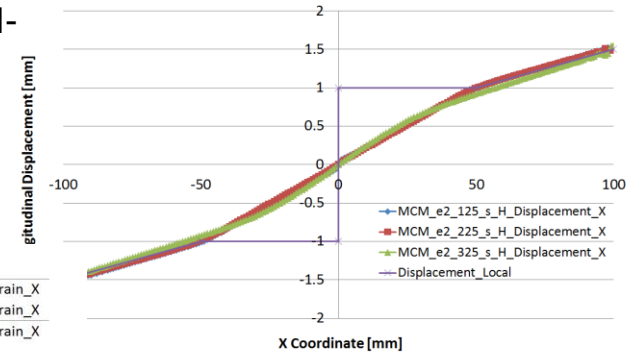
Analytical solution and the SPH-experiment 1 numerical results for longitudinal stress at $t = 3/2 \cdot L/c_e$

Numerical Experiments

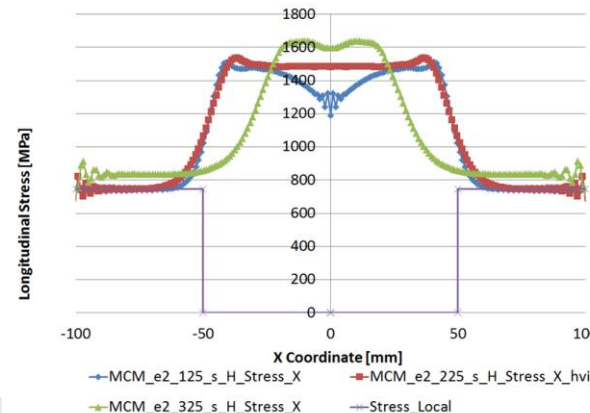
SPH Results of Experiment 2 – averaging



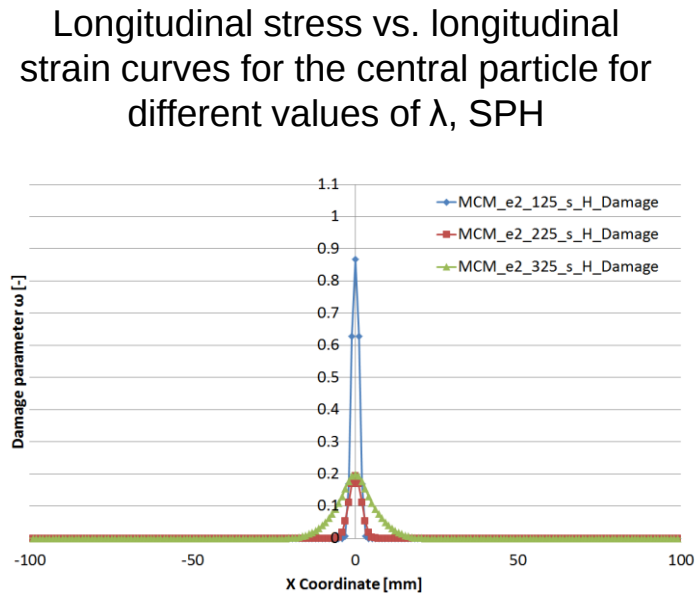
Analytical solution and the SPH-experiment 2 numerical results for longitudinal displacement at $t = 3/2 \cdot L/c_e$



Analytical solution and the SPH-experiment 2 numerical results for longitudinal strain at $t = 3/2 \cdot L/c_e$



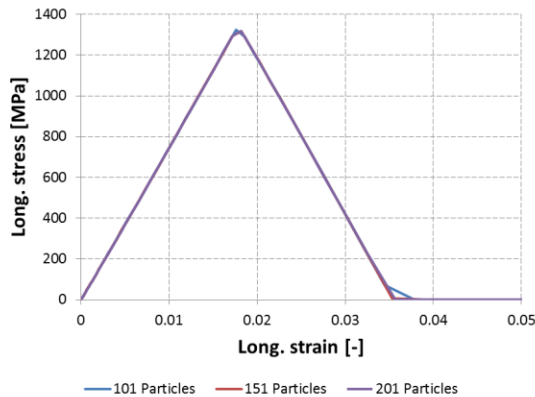
Analytical solution and the SPH-experiment 2 numerical results for longitudinal stress at $t = 3/2 \cdot L/c_e$



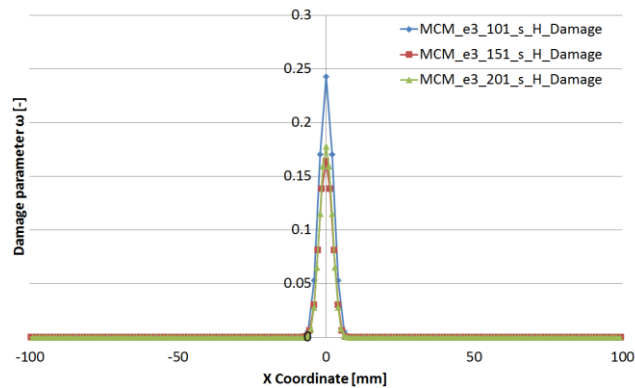
Damage distribution for different particle densities, SPH-experiment 2, response time $t = 3/2 \cdot L/c_e$

Numerical Experiments

SPH Results of Experiment 3 – constant smooth- length

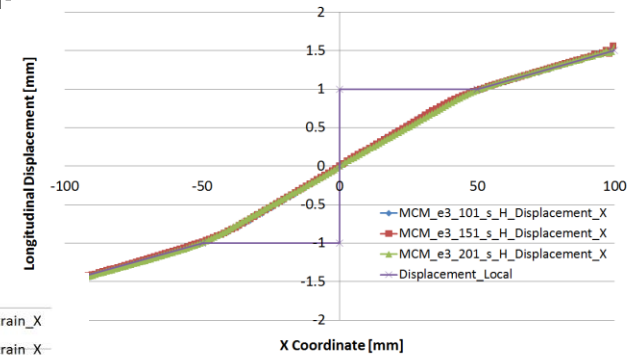


Longitudinal stress vs. longitudinal strain curves for the central particle for different values of Δp , SPH

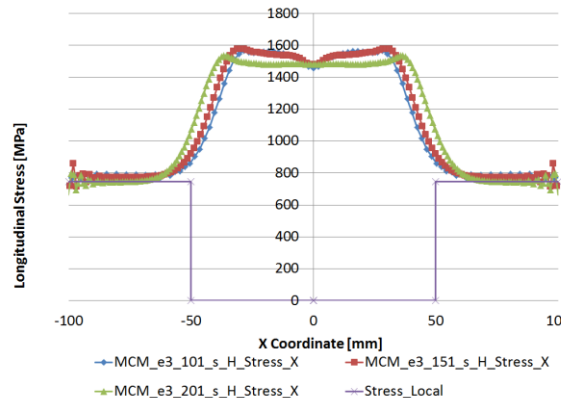
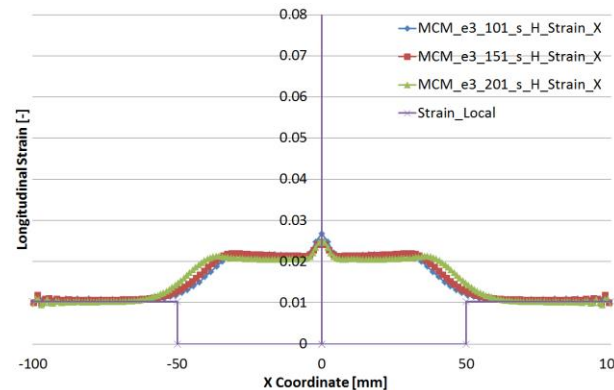


Damage distribution for different particle densities, SPH-experiment 3, response time $t = 3/2 \cdot L/c_e$

Analytical solution and the SPH-experiment 3 numerical results for longitudinal displacement at $t = 3/2 \cdot L/c_e$



Analytical solution and the SPH-experiment 3 numerical results for longitudinal strain at $t = 3/2 \cdot L/c_e$



Analytical solution and the SPH-experiment 3 numerical results for longitudinal stress at $t = 3/2 \cdot L/c_e$

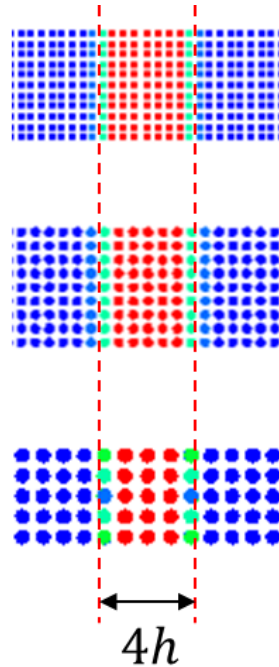
Numerical Experiments

SPH Results of Experiment 3 – constant smooth- length

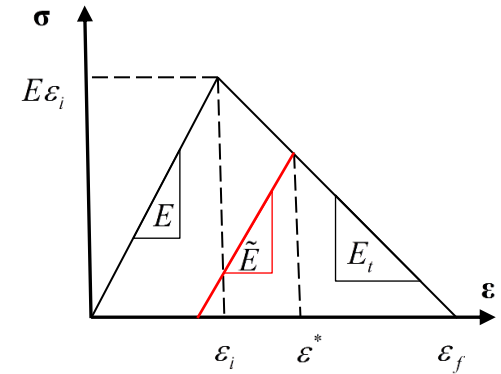
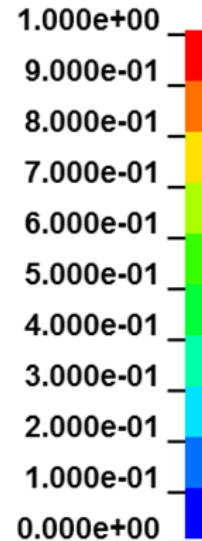
$$\Delta p = \frac{200\text{mm}}{201}$$

$$\Delta p = \frac{200\text{mm}}{151}$$

$$\Delta p = \frac{200\text{mm}}{101}$$



Fringe Levels

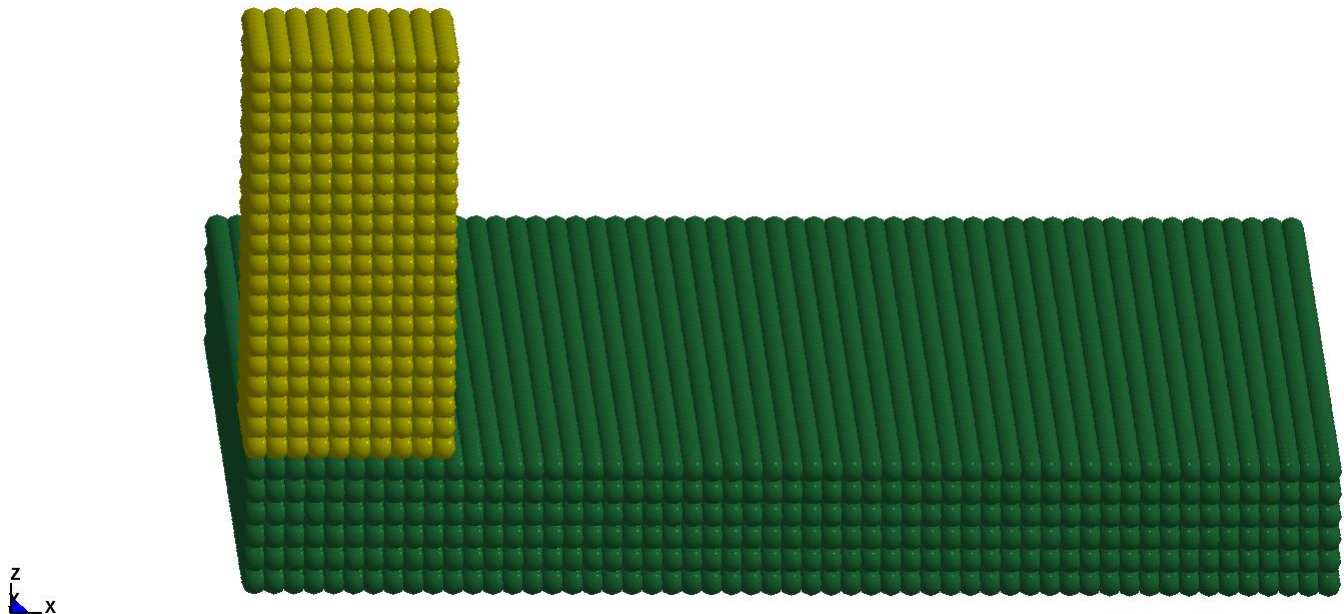


Damage distributed within a limited zone with $4h$ size around the bar symmetry plane at response time

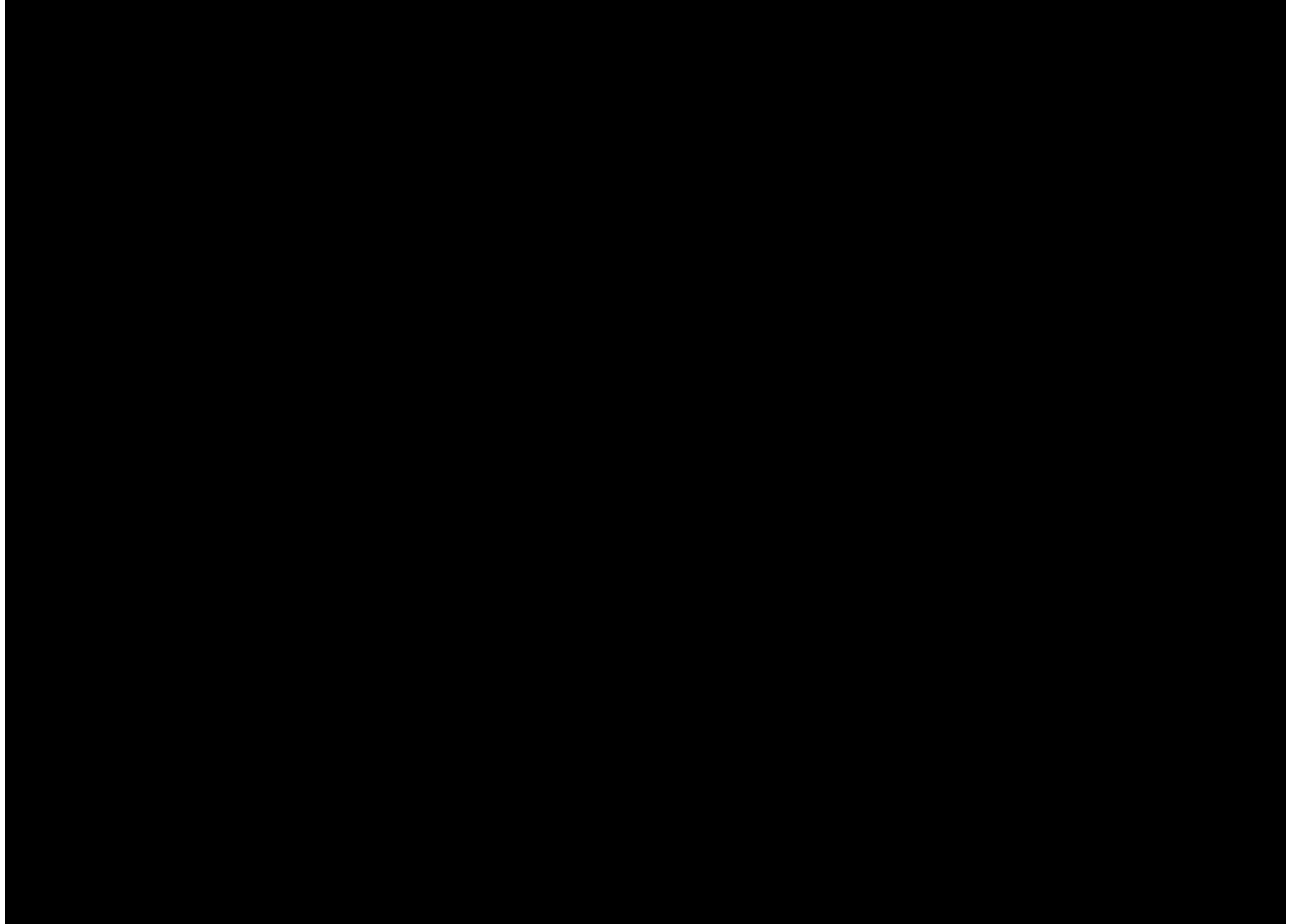
$$t = \frac{3}{2} \frac{L}{c}$$

Modelling of cube impact

- SPH code tested in a flat faced projectile impact on a 3.175mm target plate;
- Impact velocity 240m/s – 10% above the ballistic limit;



Modelling of cube impact



Conclusions and Future Work

- The strain softening process in the classic CDM combined with FEM is localised in a single element and cannot propagate;
- Localisation effects related to material strain-softening are not present with the SPH method – the method inherently nonlocal;
- Size of the softening zone was defined by the smoothing length and for a fixed smoothing length h , the strain softening was independent of the particle density;
- The future work is aimed at the orthotropic material formulation and application to composites;

Thank you for your attention

Instabilities due to Strain-Softening Solved using the SPH Method

N. Djordjevic¹, R. Vignjevic¹, T. De Vuyst¹, S. Gemkow² G,

¹Brunel University London, Kingston Lane Uxbridge, UB8 3PH United Kingdom

e-mail: nenad.djordjevic@brunel.ac.uk; v.rade@brunel.ac.uk

²Cranfield University, Cranfield, Bedfordshire MK43 0AL, United Kingdom

