

Errata to “Multiobjective Control of a Four-Link Flexible Manipulator: A Robust H_∞ Approach”

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An error appeared in the above paper [1]. Equation (17) should appear as follows:

$$\begin{aligned} & A_{cq}^T \Omega A_{cq} + \varepsilon^{-1} (N_1 + N_2 K)^T (N_1 + N_2 K) + q E^T E \\ & = (r^2 - q \gamma^{-2} Q D D^T) Q \end{aligned} \quad (17)$$

REFERENCES

- [1] Z. Wang, H. Zeng, D. W. C. Ho, and H. Unbehauen, “Multiobjective Control of a Four-Link Flexible Manipulator: A Robust H_∞ Approach,” *IEEE Trans. Contr. Syst. Technol.*, vol. 10, pp. 866–875, Nov. 2002.

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